

# SmartMod RTD Input Module

## HE359RTD100 0.1C or 0.1ohm Resolution



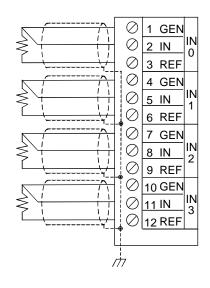
### 1 Specifications

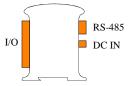
|                                     | RTD100   |   |   | RTD100  |
|-------------------------------------|--|---|---|---|
| Number of<br>Channels               | 4  | - | Conversion Time<br>(PLC Update<br>Rate)         | Determined<br>by<br>Communicat-<br>ions w/OCS               |
| Input Ranges                        | RTD Pt-100, Ni-100,<br>Pt-1000, & Ni-1000,<br>0-2000ohm,<br>0-500ohm<br>(PT, .00385) | - | Terminal Type                                   | Screw Type,<br>Removable                                    |
| Resolution                          | 0.1C or 0.1ohm   | - | Storage Temp.                                   | -40° to 85°<br>Celsius                                      |
| RTD                                 | 350microamp,   |   | Operating Temp.                                 | -10° to 60°<br>Celsius                                      |
| Excitation<br>Current               | typical  |   | Relative Humidity                               | 5 to 95%<br>Non-<br>condensing                              |
| Accuracy                            | +/-0.1% F.S.   |   | Dimensions<br>WxHxD                             | 17.5mm x<br>100mm x<br>120mm<br>0.69" x 3.94"<br>x 4.72"    |
| External<br>Power Supply<br>Voltage | 10-30Vdc   |   | Weight  | 150g (6 oz.)  |
| Required<br>Power<br>(Steady State) | 30mA @ 24Vdc,<br>typical   |   | Communications                                  | Modbus/RTU<br>(binary)<br>RS-485 half<br>duplex             |
| Required<br>Power<br>(Inrush)       | Negligible   |   | Factory Default<br>Communications<br>Parameters | 38400 baud,<br>N, 8, 1, no<br>h/s<br>Default<br>Modbus ID 1 |
| Isolation                           | 2000Vac for 60<br>seconds<br>(Input/Power &<br>Input/Comms)                          |   | Supported<br>Modbus<br>Commands                 | 1,2,3,4,5,6,8,<br>15,16                                     |
| CE & UL<br>Compliance               | See Compliance Table at http://www.heapg.com/Pages/TechSupport/ProductCert.html      |   |   |   |

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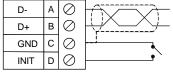
Dimensions in inches are 0.69"W x 3.95"H x 4.72"D Note: Number of I/O terminal connections vary from model to model

### 2 Wiring – I/O





| Pin# | RTD100 |      | Pin# | RTD1 | 00   |
|------|--------|------|------|------|------|
| 1    | GEN    |      | 7    | GEN  |      |
| 2    | IN     | IN 0 | 8    | IN   | IN 2 |
| 3    | REF    |      | 9    | REF  |      |
| 4    | GEN    |      | 10   | GEN  |      |
| 5    | IN     | IN 1 | 11   | IN   | IN 3 |
| 6    | REF    |      | 12   | REF  |      |



Wiring RS-485



 $\oslash$ 

Notes:

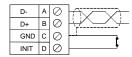
Both ends of the RS-485 network should be terminated with a 100ohm, 1/4W, 1% resistor. Many OCS controllers feature dip switches or jumpers which enable appropriate termination if the OCS is located on a network end.

MAN0840-04-EN Specifications / Installation

### 3 Init Default Setup

Communication parameters will be set to INIT default after performing the procedure:

- 1. Install jumper between INIT and GND terminals of the RS-485 port.
- 2. Apply power to Smartmod unit.
- 3. Read parameter words to see current parameters.
- 4. Write changes if necessary.



### The INIT Default RS485 Settings Are:

Modbus ID = 1 Baud rate = 9600 Parity = None Stop Bits = 1 Data Bits = 8 No handshake

Note: There are 2 types of default settings possible:

- 1. Factory default as described in section 1 (Specifications)
- 2. Default after INIT as described in section 3 (INIT Default Setup)

### 4 Configuration DATA

SmartMod Configuration settings are mapped into Modbus Register space. This configuration data may be modified with any Modbus/RTU Master device. For convenience, Horner APG has developed a variety of Cscape application files which allow an OCS (Xle, NX, LX, QX) to act as a SmartMod configurator. Initial configuration of SmartMod module should be done on an individual basis, since all modules come from the factory with a default Modbus ID of 1. Once each module on the network has its own unique Modbus ID, further configuration adjustments can be made with the entire network powered.

All configuration parameters listed below (except 40012 Channel Enable) are stored in EPROM. That means they should not be constantly rewritten.

| Configu            | Configuration Parameters – Registers 40001 through 40013 |                              |      |                                    |  |  |
|--------------------|--|------------------------------|------|------------------------------------|--|--|
| Modbus<br>Register | Description  | Description Min Max          |      | Default                            |  |  |
| 40001-<br>40005    | Reserved   |                              |      |                                    |  |  |
| 40006              | Communications<br>Parameters                             |                              |      | 38.4kbaud,<br>N, 8, 1, RTU<br>Mode |  |  |
| 40007              | Modbus ID  | 1                            | 255  | 1                                  |  |  |
| 40008              | Rx/Tx Delay (in 2mS<br>steps)                            | 0                            | 255  | 0mS                                |  |  |
| 40009              | Watchdog Timer (in 0.5s steps)                           | 0 255 10 (5s)                |      | 10 (5s)                            |  |  |
| 40010              | Modbus Coil Data   | Not Configuration Data – See |      |                                    |  |  |
| 40011              | Input Type See Table                                     |                              | able | 23 (RTD Pt-<br>100 Type)           |  |  |
| 40012              | Channel Enable   | Channel Enable See Table     |      | 255 (All<br>Channels<br>enabled)   |  |  |
| 40013              | Reserved   |                              |      |                                    |  |  |

| Register 40006 (Communications Parameters) Bit Definition |       |        |         |              |       |           |        |
|---|-------|--------|---------|--------------|-------|-----------|--------|
| Bits 7-15   | Bit 6 | Bit 5  | Bit 4   | Bit 3        | Bit 2 | Bit 1     | Bit 0  |
| Unused  | Mode  | Parity |         | Data<br>Bits | E     | Baud Rate | е      |
|   | 0 =   | Value  | Meaning | 0 = 7        | Value | Mea       | aning  |
|   | ASCII | 0      | Mark    | Data         | 0     | 1200      | baud   |
|   | Mode  | 1      | Even    | Bits         | 1     | 2400      | baud   |
|   | 1 =   | 2      | Odd     | 1 = 8        | 2     | 4800      | baud   |
|   | RTU   | 3      | Space   | Data         | 3     | 9600      | baud   |
|   | Mode  |        |         | Bits         | 4     | 19200     | ) baud |
|   |       |        |         |              | 5-7   | 38400     | ) baud |

|       | Register 40011 (Input Type) Value Definition |  |  |  |  |
|-------|--|--|--|--|--|
| Value | Input Type                                   |  |  |  |  |
| 7     | 0-2000ohm Resistance                         |  |  |  |  |
| 8     | 0-500ohm Resistance                          |  |  |  |  |
| 23    | RTD Pt-100 Type                              |  |  |  |  |
| 24    | RTD Ni-100 Type                              |  |  |  |  |
| 25    | RTD Pt-1000 Type                             |  |  |  |  |
| 26    | RTD Ni-1000 Type                             |  |  |  |  |
|       |  |  |  |  |  |

| Register 40012 (Channel Enable) Bit Definition |                         |         |         |         |  |
|--|-------------------------|---------|---------|---------|--|
| Bit 4-15                                       | Bit 3 Bit 2 Bit 1 Bit 0 |         |         |         |  |
| Unused   | Input 3                 | Input 2 | Input 1 | Input 0 |  |
|  | 0 = Disable Input       |         |         |         |  |
|  | 1 = Enable Input        |         |         |         |  |

### 5 Input/Output DATA

SmartMod Analog I/O utilizes both Modbus Registers (40001-40030) and Coils (1-11). It is possible to access all data using Registers only, because the Coils can be accessed through Register 40010.

The following tables lists all Modbus I/O data available.

| I/O Register Data (Registers 40014-40022) |                              |            |                  |          |                   |
|---|------------------------------|------------|------------------|----------|-------------------|
| Modbus<br>Register                        | Description                  | Access     | Minimum          | Maximum  | Units             |
| 40010                                     | Mirror of Coil<br>Data       | Read/Write | n/a              | n/a      | n/a               |
| 40014                                     | Cold Junction<br>Temperature | Read-only  | -1000            | 6000     | 0.01 degrees C    |
| 40015                                     | Input 0                      | Read-only  |                  |          |                   |
| 40016                                     | Input 1                      | Read-only  |                  |          |                   |
| 40017                                     | Input 2                      | Read-only  | D                | Danasala |                   |
| 40018                                     | Input 3                      | Read-only  | Depends          | Depends  | 0.1C or 0.1 ohm   |
| 40019                                     | Input 4                      | Read-only  | on Input<br>Type |          | 0.10 01 0.1 01111 |
| 40020                                     | Input 5                      | Read-only  | rype             |          |                   |
| 40021                                     | Input 6                      | Read-only  |                  |          |                   |
| 40022                                     | Input 7                      | Read-only  |                  |          |                   |

| Modbus<br>Coil | Description         | Access     |          |
|----------------|---------------------|------------|----------|
| 00001          | Open Detect Input 0 | Read/Write |          |
| 00002          | Open Detect Input 1 | Read/Write | ا        |
| 00003          | Open Detect Input 2 | Read/Write | Co       |
| 00004          | Open Detect Input 3 | Read/Write | TI       |
| 00005          | Open Detect Input 4 | Read/Write | l 'i     |
| 00006          | Open Detect Input 5 | Read/Write |          |
| 00007          | Open Detect Input 6 | Read/Write |          |
| 80000          | Open Detect Input 7 | Read/Write | ١.,      |
| 00009          | Watchdog Enabled    | Read/Write | 1        |
| 00010          | Watchdog Event      | Read/Write | ev<br>be |
| 00011          | Power-up Event      | Read/Write | DE       |

If Coil 9 (Watchdog Enabled) is set, Coil 10 (Watchdog Event) will set if the Watchdog Timeout value is exceeded. The Watchdog Timeout value is set in Register 40009. When set, Coil 10 can be reset by the controller when normal communications resumes.

Watchdog Event & Power-up

**Event Operation** 

The Power-up Event (Coil 11) is set very time the power is applied. It can e cleared by the controller if desired.

| RTD Sensor Temperature Ranges                        |                |                |  |  |
|--|----------------|----------------|--|--|
| RTD Sensor Type Minimum Temperature Maximum Temperat |                |                |  |  |
| Pt-100   | -200 degrees C | +850 degrees C |  |  |
| Ni-100   | -80 degrees C  | +180 degrees C |  |  |
| Pt-1000  | -200 degrees C | +200 degrees C |  |  |
| Ni-1000  | -60 degrees C  | +150 degrees C |  |  |

### 6 Installation / safety

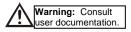
**Warning:** Remove power from the OCS controller, CAN port, and any peripheral equipment connected to this local system before adding or replacing this or any module.

- a. All applicable codes and standards should be followed in the installation of this product.
- b. Shielded, twisted-pair wiring should be used for best performance.
- c. Shields may be terminated at the module terminal strip.
- d. In severe applications, shields should be tied directly to the ground block within the panel.
- e. Use the following wire type or equivalent: Belden 8441.

For detailed installation and a <u>handy checklist</u> that covers panel box layout requirements and minimum clearances, refer to the hardware manual of the controller you are using.

When found on the product, the following symbols specify:





### 7 Technical Support

Technical Support at the following locations:

North America: Europe:

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