

X4 Micro OCS Datasheet

Model A Built-In I/O: 12 Digital In, 12 Digital Out, 4 Analog In/RTD IN, 2 Analog Out Model R Built-In I/O: 12 Digital In, 6 Relay Out, 2 PWM Out, 4 Analog In/RTD In, 2 Analog Out

MAN1138-20_X4_DS



Part Numbers

Model R: Relay & Solid State Outputs	HE-X4R
Model A: Solid State Outputs	HE-X4A

User Manual and Add-Ons

Find the documents via the Documentation Search.

Part #	Description
MAN1137	HE-X4 User Manual
HE-BAT009	3V Lithium Coin Battery
HE-XCK	Programming Cables
HE-FBD001	Ferrite core for filtering out electrical
	noise.
HE200MJ2TRM	Adapter, RJ45 (8P8C) male to 8-pos-
	ition terminal strip.

Battery Maintenance

The X4 has an advanced battery system that uses a lithium coin battery. The battery powers the real time clock when power is removed, and it is needed for register data retention. Manual **MAN1137** via the <u>Documentation Search</u> for more details on battery replacement.

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TECHNICAL SPECIFICATIONS

General Specifications

Primary Pwr. Range	24VDC +/- 20%	
Typical power Back- light 100%	190mA @ 24VDC	
Power Backlight Off	105mA @ 24VDC 135mA @ 19.2VDC	
Inrush Current	30mA < 1ms	
Real Time Clock	Battery backed; lithium coin cell CR2450	
Battery Life	7-10 years	
Clock Accuracy	+/- 90 Secs/Month	
Relative Humidity	5 to 95% Non-condensing	
Operating Temp.	-10°C to +60°C	
Storage Temp.	-20°C to +70°C	
Temperature Code	T5	
Weight	360g	
Mounting Clips	4 composite type	
Housing Material	Polycarbonate, UL rated	
Altitude Limit	Up to 2000 meters	
Environmental Ratings	1, 4X (indoor use only), 12, 12K & 13	

User Interface

Display Type	4.3" 65k Color; 350 cd/m² (nits)	
Resolution	480 x 272 pixels	
Backlight	White LED	
Real/light Lifetime	20,000 hrs to reach 50% bright-	
Backlight Lifetime	ness	
Backlight Control	Software controlled (ON/OFF)	
User-Programmable	250	
Screens/Pages		
No. of Objects /	100	
Screens		
Screen Memory	256kB	
Keypad	Touch screen	
Tactile Feedback	Optional Sound	
	Max 30 per page + touch system	
Number of Keys	and four function keys	

Connectivity

Serial Ports	1 x RS232, 1 x RS485	
485 Terminations	On-board, software controlled	
Mini USB	Programming Only	
CAN Hardware	CAN 2.0	
CAN Port Connector	RJ45 (Red)	
CAN Port Speeds	125kB, 250kB, 500kB,	
Support	1Mb/sec.	
CAN Protocols	CsCAN	
Ethernet	1 x 10Mbps/100Mbps	
	microSD (SDHC, SDXC	
Removable	IN FAT32 format, support for	
Memory In	32GB max. Application Updates,	
	Datalogging, more)	
Terminal Type	Removable 3.5 m color-coded	
1/0 Options	Onboard + SmartMod, SmartRail,	
I/O Options	SmartBlock, SmartStix	

Testing

Shock	IEC 60068-2-27
Vibration	IEC 60068-2-6
UL Environmental Rat-	Type 1, 4, 4X, 12, 12k &
ings	13 (for indoor use only)
Certifications (UL/CE)	North America Europe

Control and Logic

Control Language Support	Advanced ladder logic ; Full IEC 61131-3 languages
Logic Program Size	256kB
Non-Retentive Memory	128kB
Internal Storage Memory	16Mb
Total Program Memory	2.5Mb
Logic Scan Rate	0.4ms/kB
%I (Digital Inputs)	1024
%Q (Digital Outputs)	1024
%AI (Analog Inputs)	256
%AQ (Analog Outputs)	256
%M (Retentive Bits)	1024
%T (Temporary Bits)	1024
%R (Retentive Registers)	5000
%D (Display Bits)	250
%K (Key Bit)	4
%S (Status Bits)	16



CONTROLLER OVERVIEW

Overview of OCS



- 1. Touchscreen
- 2. Function Keys
- 3. RS232/RS485 Serial Port
- 4. CANPort (Via RJ45)
- 5. LAN Port
- 6. USB Mini-B Port
- 7. Analog I/O
- 8. DC Inputs
- 9. DC Outputs
- 10. DC Power

NOTE: See "Precautions" on page 12 about USB and grounding.

Power Wiring

NOTE: The Primary Power Range is 10VDC to 30VDC.



Primary Power Port Pins			
PIN Signal Description			
1	Ground	Frame Ground	
2	DC-	Input Power Supply Ground	
3	DC+	Input Power Supply Voltage	

DC Input / Frame

- Solid/Stranded Wire: 12-24 awg (2.5-0.2mm)
- Strip length: 0.28" (7mm)
- Torque, Terminal Hold-Down Screws: 4.5 7 in-lbs (0.50 – 0.78 N-m)
- DC- is internally connected to I/O V-, but is isolated from CAN V-. A Class 2 power supply must be used.

Power Up

1. **Optional**: Attach ferrite core with a minimum of two turns of the DC+ and DC- signals from the DC supply that is powering the controllers.



- 2. Connect to earth ground.
- 3. Apply recommended power.



DIGITAL & RELAY I/O SPECIFICATIONS

Digital DC Inputs: Models R & A

Inputs per Module	12 including 4 configurable HSC inputs	
Commons per Module		1
Input Voltage Range	12VDC	/ 24VDC
Absolute Max. Voltage	30VDC Max.	
Input Impedance	10)kΩ
Input Current	Positive Logic	Negative Logic
Upper Threshold	0.8mA	-1.6mA
Lower Threshold	0.3mA	-2.1mA
Max. Upper Threshold	8VDC	
Min. Lower Threshold	3VDC	
OFF to ON Response	0.1ms	
ON to OFF Response	0.1ms	
Number of Counters	4	
Maximum Frequency	500kHz	
Accumulator Size	32-bits each	
	Totalizer, quadrature, pulse	
Modes Supported	measurement, frequency	
would bupperted	measurement, set-point	
	controlled outputs	

Model R: Digital DC Outputs, Sinking, Sourcing

Outputs per Module	$2(P)/(M \circ r H S C)$		
· · ·	2 (PWM or HSC)		
Commons per Module		1	
Туре		Sinking	
Absolute Max. Voltage		28VDC	
Output Protection	Short Circuit		
Max. Output per Point: Sinking	0.5A		
Max. Output per Point: Sourcing	2.4mA @ 24V		
Max. Voltage Drop at Rated Current	0.25VDC		
Max Outrush	650mA		
	Min Max		
OFF to ON Time (typ- ical)	2.2µs	2.2µs + Scan Time	
ON to OFF Time (typ- ical)	13µs	13µs + Scan Tiime	
PWM Out	65kHz		
Rise Time	2.4µs (typical @ 24V)		
Fall Time	7.5µs (typical @ 24V)		

Model A: Digital DC Outputs, Sourcing

Outputs per Module	12 Including 2 Configurable PWM Outputs	
Commons per Module		2
Туре	Sourcing	
Absolute Max. Voltage	28VDC	
Output Protection	Short Circuit, Thermal, Undervoltage	
Max. Voltage Drop at Rated Current	0.25VDC	
Max Output per Point: Sourcing	0.5A @ 24VDC	
	Min	Max
OFF to ON Time (typ- ical)	300ns	500ns + Scan Time
ON to OFF Time (typ- ical)	300ns	475 = Scan Time
PWM Out	65kHz	
Rise Time	150ns Max	
Fall Time	150ns Max	

Relay Outputs: Model R

Outputs per Module	6 Relay
Relay Contact Type	Floating
Max. Output Current &	3A @ 60VAC, resistive
Voltage per Relay	3A @ 30VDC, resistive
Max. Total Output Cur-	5A continuous
rent	5A continuous
Max. Switched Power	150W
Contact Isolation to	1000VAC
Ground	1000VAC
Max. Voltage Drop at	0.5V
Rated Current	0.37
Expected Life (see	No Load : 5,000,000
derating chart)	Rated Load: 100,000
Max Switching Pata	300 CPM at no load 20 CPM at
Max. Switching Rate	rated load
Туре	Mechanical Contact
	One update per
Response Time	ladder scan plus 10 ms



ANALOG I/O SPECIFICATIONS

Analog Inputs, Models R & A

Number of Channels	4
Input Ranges	0-20mA; 4-20mA; RTD100
RTD Temperature	-50° to 200°C (-58° to 392°F)
Range	PT100 DIN
Nominal Resolution	12 Bits
Resolution	0.5°C
Safe Input Voltage	-0.5V to 12V,
Range	protection up to 24V
Input Impedance (clamped @ -0.5VDC to 12VDC)	Current Mode: 100Ω
%AI Full Scale	20mA : 32,000 full scale RTD : 20 Counts/°C
Max. Over Current	25mA
Max Error at 25°C (excluding Zero) Adjusting Filtering may Tighten	< 1.5% of full scale
Filtering	160 Hz Hash (noise) Filter, 1-128 Scan Digital Running Average Fil- ter

Analog Outputs, Models R & A

Number of Channels	2
Output Ranges	4-20mA
Nominal Resolution	12 Bits
Update Rate	Once per PLC scan
Max. Error at 25°C (Excluding Zero)	< 1.5% of full scale
Maximum 20mA Load	500Ω
% AQ Full Scale	32,000
Protection	Protect against miswire up to 24VDC auto-recover



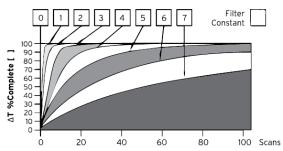
WIRING: INPUTS AND OUTPUTS

Relay Life

Analog Inputs Information

Raw input values for channels 1-4 are found in the registers as Integer- type data with a range from 0 - 32000.

Analog inputs may be filtered digitally with the Filter Constant found in the Cscape Hardware Configuration for Analog Inputs. Valid filter values are 0-7 and act according to the following chart:



Data Values		
Input Mode:	Data Format, 12-bit INT:	
0-20mA, 4-20mA	0-32000	
RTD	20 Counts/ °C	

Relay Life Expectancy

WARNING: Exposure to some chemicals may degrade the sealing proper- ties of materials used in the Tyco relay PCJ. **Cover/Case & Base**: Mistubishi engineering Plastics Corp. 5010GN6-30 or 5010GN6-30 M8 (PBT)

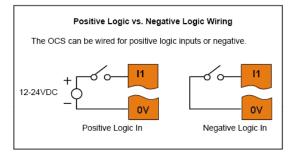
Sealing Material: Kishimoto 4616-50K (I part epoxy resin)

Inserting and Removing Connectors

To Insert: Using a small screwdriver, firmly press on connector on one end and then the other until connector clicks into place. Ensure connector is firmly seated.

To Remove: Use a small screwdriver on each side of connector to gently pry up the connector.

Digital Inputs



Digital inputs may be wired in either a Positive Logic or Negative Logic fashion as shown. The setting in the Cscape Hardware Configuration for the Digital Inputs must match the wiring used in order for the correct input states to be registered.

Built-In I/O: Models R & A

Fixed Address	I/O Function	Model R	Model A
	Digital Inputs	1-12	1-12
%I	Reserved	13-32	13-32
	Digital Outputs	1-2	1-12
	Relay Outputs	3-8	
%Q	Reserved	9-24	13-24
	Analog Inputs	1-4	1-4
%AI	Reserved	5-12	5-12
	Analog Outputs	1-2	1-2
%AQ	Reserved	3-16	3-16



J1 & J2 WIRING

J1 Wiring: Model A - Digital Out

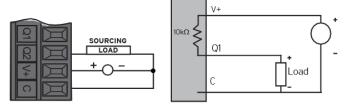
POSITION/PIN		DIGITAL MODEL
1	Q1 (%Q1)	Dig. Out 1 (PWM)
2	Q2 (%Q2)	Dig. Out 2 (PWM)
3	Q3 (%Q3)	Dig. Out. 3
4	Q4 (%Q4)	Dig Out. 4
5	V+	External V+
6	С	Common
7	Q5 (%Q5)	Dig Out. 5
8	Q6 (%Q6)	Dig Out. 6
9	Q7 (%Q7)	Dig Out. 7
10	Q8 (%Q8)	Dig Out. 8
11	Q9 (%Q9)	Dig Out. 9
12	Q10 (%Q10)	Dig Out. 10
13	Q11 (%Q11)	Dig Out.11
14	Q12 (%Q12)	Dig Out. 12
15	V+	External V 2 +
16	С	Common

Q1	Д	
ß	E	
ပ္ထ	A	
8	因	
4	E	+0-
ဂ	因	
ß	因	
ß	因	
Q7	E	
Q	E	
Q9	E	
Q10 Q11	E	LOAD
Q	E	LOAD
Q12 V+	Ц	LOAD
4	Ц	+0-
\circ		

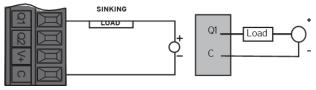
NOTE: Internal 10k Ω resistors between: V+ and Q1; V+ and Q2

Sinking & Sourcing Wiring on Model R

Model R: Sourcing Outputs [2.4mA @ 24V]

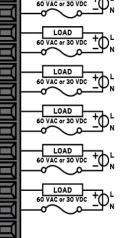


Model R: Sinking Outputs [Outputs can sink 500mA]



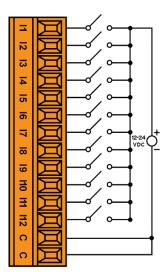
J1 Wiring: Model R - Relay / Digital Out

Р	OSITION/PIN	DIGITAL MODEL	
1	R1 (%Q3)	Relay 1 N.O.	
2	C1 (%Q3)	Relay 1 C	
3	R2 (%Q4)	Relay 2 N.O.	
4	C2 (%Q4)	Relay 2 C	
5	R3 (%Q5)	Relay 3 N.O.	
6	C3 (%Q5)	Relay 3 C	
7	R4 (%Q6)	Relay 4 N.O.	
8	C4 (%Q6)	Relay 4 C	
9	R5 (%Q7)	Relay 5 N.O.	
10	C5 (%Q7)	Relay 5 C	
11	R6 (%Q8)	Relay 6 N.O.	
12	C6 (%Q8)	Relay 6 C	
13	Q1 (%Q1)	Dig. OUT 1	
14	Q2 (%Q2)	Dig. OUT 2	
15	V+	External V+	
16	С	Common	•



J2 Wiring: Models R & A - Digital Input

POSITION/PIN		DIGITAL MODEL
1	1 (% 1)	Dig. IN 1
2	12 (%12)	Dig. IN 2
3	13 (%13)	Dig. IN 3
4	4 (% 4)	Dig. IN 4
5	15 (%15)	Dig. IN 5
6	16 (%16)	Dig. IN 6
7	17 (%17)	Dig. IN 7
8	18 (%18)	Dig. IN 8
9	19 (%19)	Dig. IN 9 (HSC)
10	110 (%110)	Dig. IN 10 (HSC)
11	11 (% 11)	Dig. IN 11 (HSC)
12	l12 (%l12)	Dig. IN 12 (HSC)
13	С	Common
14	С	Common





J3 WIRING - Models A & R

4 X 4 20mA Input / 4-20mA Output

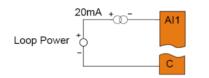
PIN Wire
2 R1+ (%Al1)
3 AI2 (%AI2)
4 R2+ (%Al1)
5 (AI3/%AQ1)
6 R3+ or AQ1 (AI3/%AQ1)
7 AI4 (AI4/%AQ2)
8 R4+ or AQ2 If AQ1 is used, RTD3 is una (AI4/%AQ2) If AQ2 is used, RTD4 is una
9 C

RTD: 2 x 3 - Wire RTD & 2 x 4 4-20mA Output

PIN	Wire	Connection
1	Al1 (%Al1)	RTD Sense
2	R1+ (%Al1)	RTD Excitation
3	AI2 (%AI2)	RTD Sense
4	R2+ (%AI2)	RTD Excitation
5	AI3 (AI3/%AQ1)	No Connection
6	R3+ or AQ1 (Al3/%AQ1)	mA Output
7	AI4 (AI4/%AQ2)	No Connection
8	R4+ or AQ2 (AI4/%AQ2)	mA Output
9	С	Common

Universal Wiring Schematic

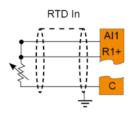
20mA Analog In - Not Self Powered





4 - 20mA Analog Out

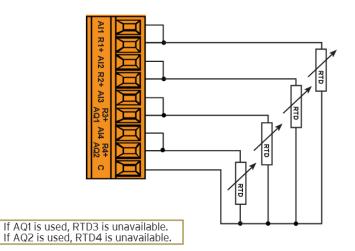






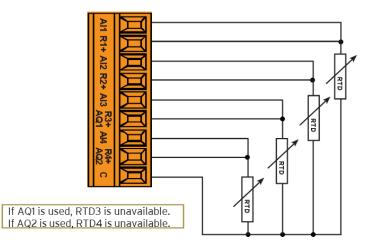
RTD: 4 x 2 - Wire RTD Connection

PIN	Wire	Connection
1	Al1 (%Al1)	RTD Sense
2	R1+ (%Al1)	RTD Excitation
3	AI2 (%AI2)	RTD Sense
4	R2+ (%Al1)	RTD Excitation
5	AI3 (AI3/%AQ1)	RTD Sense
6	R3+ or AQ1 (AI3/%AQ1)	RTD Excitation
7	AI4 (AI4/%AQ2)	RTD Sense
8	R4+ or AQ2 (AI4/%AQ2)	RTD Excitation
9	С	Common

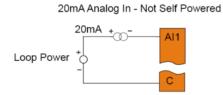


RTD: 4 x 3 - Wiring RTD Connection

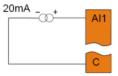
PIN	Wire	Connection
1	Al1 (%Al1)	RTD Sense
2	R1+ (%Al1)	RTD Excitation
3	AI2 (%AI2)	RTD Sense
4	R2+ (%Al1)	RTD Excitation
5	AI3 (AI3/%AQ1)	RTD Sense
6	R3+ or AQ1 (Al3/%AQ1)	RTD Excitation
7	AI4 (AI4/%AQ2)	RTD Sense
8	R4+ or AQ2 (AI4/%AQ2)	RTD Excitation
9	С	Common



Universal Wiring Schematic

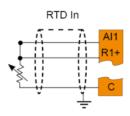


20mA Analog In - Self Powered



4 - 20mA Analog Out







COMMUNICATIONS

Serial Communication

MJ1/2 Serial Ports



2 Serial Ports on 1 Module Jack (8posn)

MJ1: RS-232 w/Full Handshaking **MJ2**: RS-485 Half-Duplex - RS-485 termination and biasing via System Menu or System Register

	MJ1 & MJ2 PINS		
PIN	SIGNAL	DIRECTION	
8	TXD	OUT	
7	RXD	IN	
6	0V	COMMON	
5	+5V @ 60mA	OUT	
4	RTS	OUT	
3	CTS	IN	
2	RX-/TX-	IN / OUT	
1	RX+/TX+	IN / OUT	

NOTE: Attach optional Ferrite Core (HE-FBD001) with a minimum of two turns of serial cable.

Ethernet



Green LED indicates link - when illuminated, data communication is available. Yellow LED indicates activity - when flashing, data is in transmission.

CAN Communications



Modular jack (8 posn RJ45)

	MJ1 & MJ2 PINS		
PIN	SIGNAL	DIRECTION	
8	TXD	OUT	
7	RXD	IN	
6	0V	COMMON	
5	+5V @ 60mA	OUT	
4	RTS	OUT	
3	CTS	IN	
2	RX-/TX-	IN / OUT	
1	RX+/TX+	IN/OUT	

The CAN port is provided via the single 8-position modular jack labeled "CAN". It may be used to communicate with other OCS products using Horner's CsCAN protocol. Additionally, remote expansion I/O such as SmartRail, SmartBlock, and SmartStix may be implemented using the CsCAN protocol.

Termination for the CAN port may be enabled from the System Menu or System Register. This should only occur if the X4 is at either end of the CAN network. Only the two devices on either end of the CAN network should be terminated.

Discreet Wiring

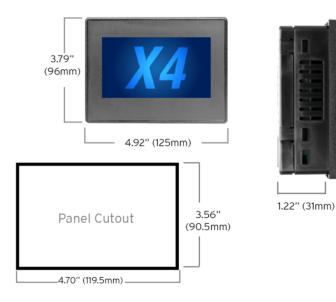
For CAN or serial connections the <u>HE200MJ2TRM</u> accessory will provide a modular connector to wiring block adapter for installations that require descreet wiring.





DIMENSIONS & INSTALLATION

X4 Dimensions



Panel Tolerance +/- 0.5mm

Installation Procedure

- This equipment is panel mounted and is meant to be installed in an enclosure suitable for the environment, such that the back of the equipment is only accessible with the use of a tool.
- Requires a Class 2 power source.
- This equipment is suitable for use in Class I, Division 2, Groups A, B, C and D; Class II, Division 2 Groups F and G; and Class III Hazardous Locations or Non-Hazardous Locations only.
- The X4 utilizes a clip installation method to ensure a robust and watertight seal to the enclosure. Follow the steps below for the proper installation and operation of the unit.

Please following the steps below for the proper installation and operation of the unit.

- Carefully locate an appropriate place to mount the X4. Be sure to leave enough room at the top of the unit for insertion and removal of the microSD[™] card.
- Carefully cut the host panel per the diagram, creating a 90.5mm x 119.5mm with a cutout tolerance of +/-0.5mm opening into which the X4 is to be installed. If the opening is too large, water may leak into the enclosure, potentially damaging the unit. If the opening is too small, the OCS may not fit through the hole without damage.
- 3. Remove any burrs/sharp edges and ensure the panel is not warped in the cutting process.
- Install and tighten the four mounting clips (provided in the box) until the gasket forms a tight seal. For standard composite mounting clips (included with product). NOTE: Torque rating is 2-3 in-lbs (0.23-0.34 Nm). For optional metal mounting clips, use a torque rating of 4-8 in-lbs (0.45-0.90 Nm).
- 5. Connect communications cables to the serial port, USB ports, and CAN port as required.



SAFETY & MAINTENANCE

Warnings

- To avoid the risk of electric shock or burns, always connect the safety (or earth) ground before making any other connections.
- 2. To reduce the risk of fire, electrical shock, or physical injury, it is strongly recommended to fuse the voltage measurement inputs. Be sure to locate fuses as close to the source as possible.
- 3. Replace fuse with the same type and rating to provide protection against risk of fire and shock hazards.
- 4. In the event of repeated failure, do NOT replace the fuse again as repeated failure indicates a defective condition that will NOT clear by replacing the fuse.
- 5. Only qualified electrical personnel familiar with the construction and operation of this equipment and the hazards involved should install, adjust, operate, or service this equipment.
- 6. Read and understand this manual and other applicable manuals in their entirety before proceeding. Failure to observe this precaution could result in severe bodily injury or loss of life.
- 7. **WARNING** Battery may explode if mistreated. Do not recharge, disassemble, or dispose of in fire.
- 8. WARNING EXPLOSION HAZARD Batteries must only be changed in an area known to be non-hazardous.
- 9. **WARNING** Do not disconnect while circuit is live unless are is know to be non-hazardous.

FCC Compliance

This device complies with Part 15 of the FCC Rules. Operation is subject to the following

two conditions:

- 1. This device may not cause harmful interference.
- 2. This device must accept any interference received, including interference that may cause undesired operation.

Technical Support

North America

1 (317) 916-4274 (877) 665-5666 www.hornerautomation.com techsppt@heapg.com

Europe

+353 (21) 4321-266 www.hornerautomation.eu technical.support@horner-apg.com

Precautions

All applicable codes and standards need to be followed in the installation of this product. Adhere to the following safety precautions whenever any type of connection is made to the module:

- 1. Connect the safety (earth) ground on the power connector first before making any
- 2. other connections.
- 3. When connecting to the electric circuits or pulse-initiating equipment, open their
- 4. related breakers.
- 5. Do NOT make connection to live power lines.
- 6. Make connections to the module first; then connect to the circuit to be monitored.
- 7. Route power wires in a safe manner in accordance with good practice and local codes.
- 8. Wear proper personal protective equipment including safety glasses and insulated gloves when making connections to power circuits.
- 9. Ensure hands, shoes, and floor are dry before making any connection to a power line.
- 10. Make sure the unit is turned OFF before making connection to terminals.
- 11. Make sure all circuits are de-energized before making connections.
- 12. Before each use, inspect all cables for breaks or cracks in the insulation. Replace
- 13. immediately if defective.
- 14. Use copper conductors in Field Wiring only, 60/75°C.
- 15. Use caution when connecting controllers to PCs via serial or USB. PCs, especially laptops,may use "floating power supplies" that are ungrounded. This could cause a damaging voltage potential between the laptop and controller. Ensure the controller and laptop are grounded for maximum protection. Consider using a USB isolator due to voltage potential differences as a preventative measure.