

# XL4 Datasheet - Model 3

## 12 DC In, 12 DC Out, 2 – 12-bit Analog In

MAN1145-21-EN\_XL4\_Mod3



### Part Numbers

Global Part Number	HE-XC1E3
European Part Number	HEXT251C113

### User Manual and Add-Ons

Find the documents via the [Documentation Search](#).

Part #	Description
MAN0964	XL4 & XL4 Prime User Manual
MAN1142	Rechargeable Battery Manual
HE-BAT019	Rechargeable 3.6V Lithium Battery
HE-XCK	Programming Cables
HE-XDAC	2 channel Analog Output I/O option kit, selectable 0-10V, +/-10V, 4-20mA.
HE-XDAC107	4 channel Analog Output I/O option kit, selectable 0-10V, +/-10V, 4-20mA.
HE-XKIT	Blank I/O Board
HE200MJ2TRM	Adapter, RJ45 (8P8C) male to 8-position terminal strip.
HE-FBD001	Ferrite core for filtering out electrical noise.

### Battery Maintenance

The XL4 has an advanced battery system that uses a rechargeable lithium battery. The battery powers the real time clock when power is removed, and it is needed for register data retention. Manual **MAN0964** via the [Documentation Search](#) for more details on battery replacement.

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## TECHNICAL SPECIFICATIONS

### General Specifications

Typical Power Backlight 100%	239mA @ 10V (2.39W) 103mA @24V (2.47W)
Power Backlight Off	18mA @ 24VDC (0.43W)
Power Backlight @ 50%	24mA @ 24VDC (0.58W)
Required Power (Steady State)	189mA @ 24VDC (4.54W) 426mA @ 10VDC (4.26W)
Required Power (Inrush)	2A for < 1ms @ 24VDC, DC switched
Heater Option*	250mA with heater* (24VDC)
Primary Power Range	10 - 30VDC 10 - 24VDC (with heater*)
Max. Current	500mA, Class 2 750mA, Class 2 (with heater*)
Relative Humidity	5 to 95%, Non-Condensing
Clock Accuracy	+ / - 20 ppm maximum at 25°C (+/- 1 min/month)
Real Time Clock	Battery Backed, Rechargeable Lithium
Operating Temperature	-10°C to +60°C -40°C to +60°C (with heater*)
Storage Temperature	-20°C to +60°C
Weight	12 oz / 340g (without I/O)
Altitude	Up to 2000m
Pollution Degree	Degree 2 Rating
Certifications (UL/CE)	<a href="#">North America</a> or <a href="#">Europe</a>
Enclosure Type	1, 3R, 4, 4X, 12, 12K & 13

\*Heater Option (Model # plus "-22")

### Control and Logic

Control Lang. Support	Register-Based Advanced Ladder Logic; Variable-Based Advanced Ladder; IEC 61131-3 Languages
Logic Program Size	2MB, maximum
Scan Rate	.04ms/kB
Digital Inputs	2048
Digital Outputs	2048
Analog Inputs	512
Analog Outputs	512
Gen. Purpose Registers	50,000 (words) Retentive 16,384 (bits) Retentive 16,384 (bits) Non-retentive

### User Interface

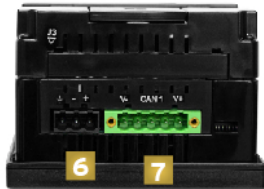
Display Type	3.5" TFT Color
Screen Brightness	640cd/m2 (nits)
Resolution	QVGA (320 x 240)
Color	16-bit (65,535)
User-Program. Screens	1023 max pages; 1023 objects per page
Backlight	LED - 50,000 hour life
Brightness Control	0-100% via System Register %SR57
Number of Keys	5

### Connectivity

Serial Ports	1 RS-232 and 1 RS-485 on singular Modular Jack
USB mini-B	USB 2.0 (480MHz) Programming & Data Access
USB A (500mA max)	USB 2.0 (480MHz) for USB flash drives (2TB)
CAN Port Isolated 1kV	Remote I/O, Peer-to-peer Comms, Cscape
CAN Protocols	CsCAN, CANopen, DeviceNet, J1939
Ethernet	10/100 Mb (Auto-MDX)
Ethernet Protocols	TCP/IP, Modbus TCP, FTP, SMTP, EGD, ICMP, ASCII
Remote I/O	SmartRail, SmartStix, SmartBlock, SmartMod
Removable Memory	microSD, SDHC, SDXC IN FAT32 format, support for 32GB max. Application Updates, Datalogging

# CONTROLLER OVERVIEW

## Overview of OCS

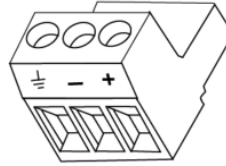


1. Touchscreen
2. High Capacity microSD Slot
3. RS232/RS485 Serial Port
4. CAN Port (via RJ485)
5. LAN Port
6. USB Mini-B Port
7. Analog I/O
8. DC Inputs
9. DC Outputs
10. DC Power

**NOTE:** See "Precautions" on page 9 about USB and grounding.

## Power Wiring

**NOTE:** The Primary Power Range is 10VDC to 30VDC.



Primary Power Port Pins		
PIN	Signal	Description
1	Ground	Frame Ground
2	DC-	Input Power Supply Ground
3	DC+	Input Power Supply Voltage

### DC Input / Frame

- Solid/Stranded Wire: 12-24 awg (2.5-0.2mm)
- Strip length: 0.28" (7mm)
- Torque, Terminal Hold-Down Screws: 4.5 – 7 in-lbs (0.50 – 0.78 N-m)
- DC- is internally connected to I/O V-, but is isolated from CAN V-. A Class 2 power supply must be used.

### Power Up

1. **Optional:** Attach ferrite core with a minimum of two turns of the DC+ and DC- signals from the DC supply that is powering the controllers. See page 1.



2. Connect to earth ground.
3. Apply recommended power.

## MODEL 3 SPECIFICATIONS

### Digital DC Input

Inputs per Module	12 Including 4 Configurable HSC Inputs	
Commons per Module	1	
Input Voltage Range	12VDC / 24VDC	
Absolute Max. Voltage	30VDC Max.	
Input Impedance	10k $\Omega$	
Input Current	Positive Logic	Negative Logic
Upper Threshold	0.8mA	-1.6mA
Lower Threshold	0.3mA	-2.1mA
Max. Upper Threshold	8VDC	
Min. Lower Threshold	3VDC	
OFF to ON Response	1ms	
ON to OFF Response	1ms	
High Speed Counter Max Freq*	1MHz	

### Digital DC Outputs

Outputs per Module	12 Including 2 Configurable PWM Outputs
Commons per Module	1
Output Type	Sourcing / 10k $\Omega$ Pull-Down
Output Frequency	500kHz
Absolute Max. Voltage	28VDC Max.
Output Protection	Short Circuit
Max. Output Current/Point	0.5A
Max. Total Current	4A Continuous
Max. Output Supply Voltage	30VDC
Min. Output Supply Voltage	10VDC
Max. Voltage Drop at Rated Current	0.25VDC
Max. Inrush Current	650mA per Channel
Min. Load	None
OFF to ON Response	1ms
ON to OFF Response	1ms
Output Characteristics	Current Sourcing (Pos. Logic)
PWM Out	$\approx$ 5kHz
Rise Time	50 - 115 $\mu$ s
Fall Time	8-20 $\mu$ s

### Analog Inputs

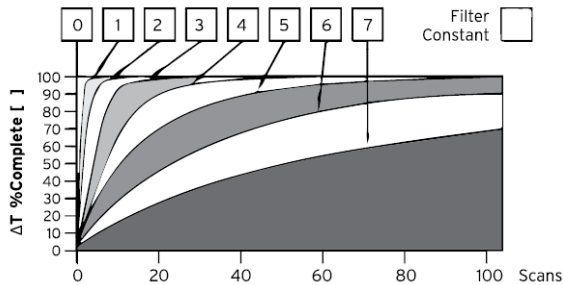
Number of Channels	2
Input Ranges	0 – 10VDC 0 – 20mA 4 – 20mA
Safe Input Range	-0.5V to +12V
Input Impedance (Clamped @ -0.5 VDC to 12 VDC)	Current Mode: 100 $\Omega$ Voltage Mode: 500k $\Omega$
Nominal Resolution	12 Bits
%AI full scale	0V, 20mA, 100mV: 32,000 counts full scale
Max. Over-Current	35mA
Conversion Speed	All channels converted once per ladder scan
Max. Error @25°C (excluding zero)	4-20mA 1.00% 0-20mA 1.00% 0-10VDC 0.50%
Filtering	160Hz hash (noise) filter 1-128 scan digital running average filter

# WIRING: INPUTS AND OUTPUTS

## Analog Inputs Information

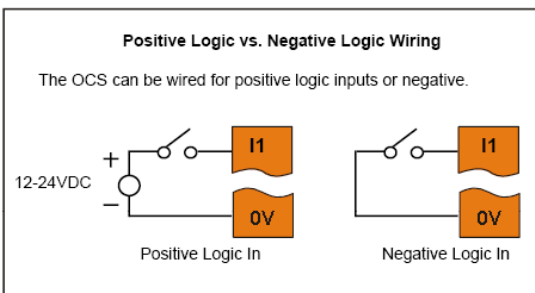
Raw input values for channels 1-4 are found in the registers as Integer-type data with a range from 0 – 32000.

Analog inputs may be filtered digitally with the Filter Constant found in the Cscape Hardware Configuration for Analog Inputs. Valid filter values are 0-7 and act according to the following chart:



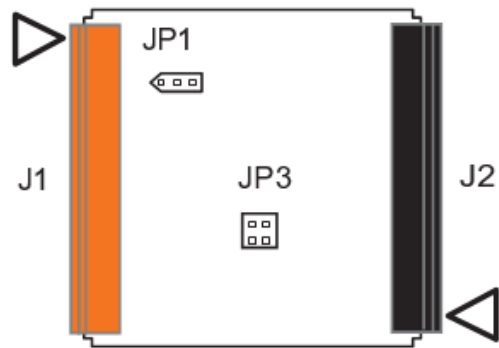
Data Values	
Input Mode:	Data Format, 12-bit INT:
0-20mA, 4-20mA	0-32000
0-10V	0-32000

## Digital Inputs



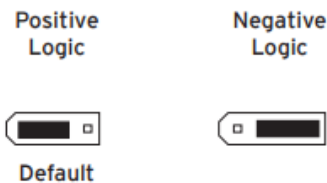
Digital inputs may be wired in either a Positive Logic or Negative Logic fashion as shown. The setting in the Cscape Hardware Configuration for the Digital Inputs must match the wiring used in order for the correct input states to be registered. When used as a normal input and not for high speed functions, the state of the input is reflected in registers %I1 – %I12.

## Jumper Settings for Model 3

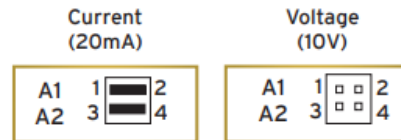


Location of I/O jumpers (JP1 & JP3) and wiring connectors (J1, J2, J3 & J4) with back cover removed.

### JP1 Digital DC Inputs



### JP3 Analog In



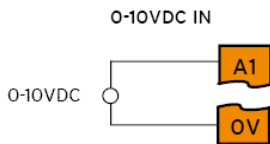
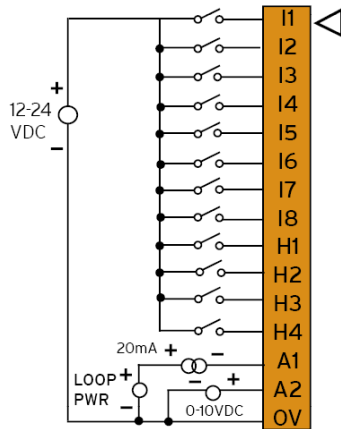
**NOTE:** The Cscape Module Configuration must match the selected I/O (JP) jumper settings.  
**NOTE:** When using JP3 (A1-A2), each channel can be independently configured.

## Back Panel Torque Ratings

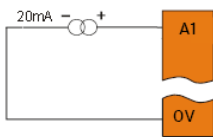
- XLE/XLT: 3.0 - 4.0 in-lbs (0.34 - 0.45 N-m)
- XL4/XL4 Prime: 3.0 - 4.0 in-lbs (0.34 - 0.45 N-m).
- EXL6/XL6 Prime: 3.0 - 4.0 in-lbs (0.34 - 0.45 N-m)
- EXLW/ XLW Prime: 3.0 - 3.5 in-lbs (0.34 - 0.40 N-m)
- XL7/XL7 Prime: 3.0 - 3.5 in-lbs (0.34 - 0.40 N-m)
- EXL10/XL10 Prime: 3.0 - 3.5 in-lbs (0.34 - 0.40 N-m)

## J1 Wiring - Digital In / Analog In

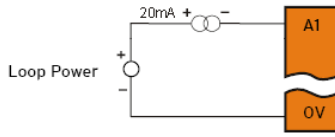
J1 (Orange) Name	
I1 (%I1)	Digital In 1
I2 (%I2)	Digital In 2
I3 (%I3)	Digital In 3
I4 (%I4)	Digital In 4
I5 (%I5)	Digital In 5
I6 (%I6)	Digital In 6
I7 (%I7)	Digital In 7
I8 (%I8)	Digital In 8
H1 (%I9)	HSC1 / Dig. In 9
H2 (%I10)	HSC2 / Dig. In 10
H3 (%I11)	HSC3 / Dig. In 11
H4 (%I12)	HSC4 / Dig. In 12
A1 (%AI1)	Analog In 1
A2 (%AI2)	Analog In 2
OV	Common



20mA Analog In - Self Powered



20mA Analog In - Not Self Powered



## Built-In I/O

The I/O is mapped into OCS Register space, in three separate areas: Digital/Analog I/O, High-Speed Counter I/O, and High-speed Output I/O. Digital/Analog I/O location is fixed starting at 1, but the high-speed counter and high-speed output references may be mapped to any open register location.

Digital and Analog I/O Function Registers	
Digital Inputs	%I1-12
Reserved	%I13-31
ESCP Alarm	%I32
Digital Outputs	%Q1-12
Reserved	%Q13-24
Analog Inputs	%AI1-2
Reserved	%AI3-12
Analog Outputs	n/a
Reserved	%AQ1-8

## Wiring Details

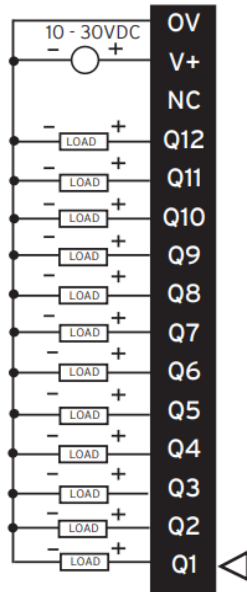
**Solid/Stranded Wire:** 12-24 awg (2.5-0.2mm<sup>2</sup>).

**Strip Length:** 0.28" (7mm).

**Torque, Terminal Hold-Down Screws:** 4.5 – 7 in-lbs (0.50 – 0.78 N-m).

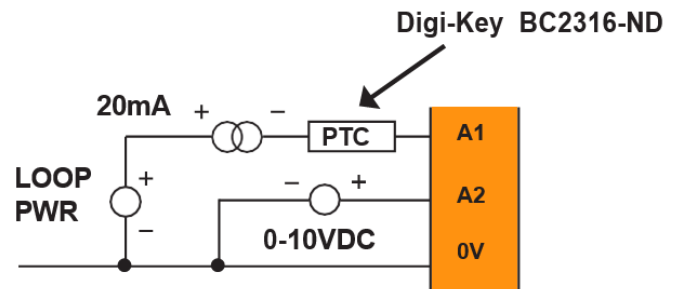
## J2 Wiring - Digital Out

J2 (Black) Name	
OV	Common
V+	V+
NC	No Connect
Q12 (%Q12)	Digital Out 12
Q11 (%Q11)	Digital Out 11
Q10 (%Q10)	Digital Out 10
Q9 (%Q9)	Digital Out 9
Q8 (%Q8)	Digital Out 8
Q7 (%Q7)	Digital Out 7
Q6 (%Q6)	Digital Out 6
Q5 (%Q5)	Digital Out 5
Q4 (%Q4)	Digital Out 4
Q3 (%Q3)	Digital Out 3
Q2 (%Q2)	Dig. Out 2 / PWM 2
Q1 (%Q1)	Dig. Out 1 / PWM 1



## Analog Input Transorb Failure

A common cause of Analog Input Transorb Failure on Analog Inputs Model 2, 3, 4 & 5: If a 4-20mA circuit is initially wired with loop power, but without a load, the analog input could see 24VDC. This is higher than the rating of the transorb. This can be solved by NOT connecting loop power prior to load connection, or by installing a low-cost PTC in series between the load and analog input.

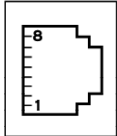




# COMMUNICATIONS

## Serial Communication

### MJ1/2 Serial Ports



2 Serial Ports on 1 Module Jack (8posn)

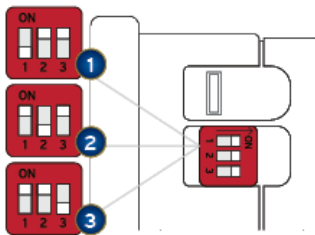
**MJ1:** RS-232 w/Full Handshaking

**MJ2:** RS-485 Half-Duplex

PIN	MJ1 PINS		MJ2 PINS	
	SIGNAL	DIRECTION	SIGNAL	DIRECTION
8	TXD	OUT	--	--
7	RXD	IN	--	--
6	0V	GROUND	0V	GROUND
5	+5V @ 60mA	OUT	+5V @ 60mA	OUT
4	RTS	OUT	--	--
3	CTS	IN	--	--
2	--	--	RX- / TX-	IN / OUT
1	--	--	RX+ / TX+	IN / OUT

**NOTE:** Attach optional Ferrite Core (HE-FBD001) with a minimum of two turns of serial cable.

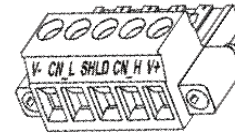
## Dip Switches



DIP Switches			
PIN	NAME	FUNCTION	DEFAULT
1	RS-485 Termination	ON = Terminated	OFF
2	Spare	Always OFF	OFF
3	Factory Use	Always OFF	OFF

The DIP switches are used to provide a built-in termination to the MJ2 port if needed. The termination for these ports should only be used if this device is located at either end of the multidrop/daisy-chained RS-485 network.

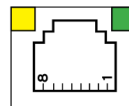
## CAN Communications



CAN Pin Assignments		
PIN	SIGNAL	DESCRIPTION
1	V-	CAN Ground – Black
2	CN_L	CAN Data Low – Blue
3	SHLD	Shield Ground – None
4	CN_H	CAN Data High – White
5	V+ (NC)	No Connect – Red

- **Solid/Stranded Wire:** 12-24 awg (2.5-0.2mm).
- **Strip Length:** 0.28" (7mm).
- Locking spring-clamp, two-terminators per conductor.
- **Torque, Terminal Hold-Down Screws:** 4.5 – 7 in-lbs (0.50 – 0.78 N-m).
- V+ pin is not internally connected, the SHLD pin is connected to Earth ground via a 1MΩ resistor and 10 nF capacitor.

## Ethernet



**Green LED indicates link** - when illuminated, data communication is available.  
**Yellow LED indicates activity** - when flashing, data is in transmission.

## DIMENSIONS & INSTALLATION

### XL4 & XL4 Prime Dimensions



\* +/- 0.1mm cutout tolerance

### Installation Information

- The XL4/XL4 Prime utilizes a clip installation method to ensure a robust and watertight seal to the enclosure. Please follow the steps below for the proper installation and operation of the unit.
- This equipment is suitable for Class I, Division 2, Groups A, B, C and D or non-hazardous locations only.
- Digital outputs shall be supplied from the same source as the operator control station.
- Jumpers on connector JP1 shall not be removed or replaced while the circuit is live unless the area is known to be free of ignitable concentrations of flammable gases or vapors.
- **WARNING-** The USB ports are for operational maintenance only. Do not leave permanently connected unless area is known to be non-hazardous.

### Installation Procedure

1. Carefully locate an appropriate place to mount the OCS. Be sure to leave enough room at the top of the unit for insertion and removal of the microSD™ card.
2. Carefully cut the host panel per the diagram, creating a 92mm x 92mm +/-0.1mm opening into which the OCS may be installed. If the opening is too large, water may leak into the enclosure, potentially damaging the unit. If the opening is too small, the OCS may not fit through the hole without damage.
3. Remove any burrs and or sharp edges and ensure the panel is not warped in the cutting process.
4. Remove all Removable Terminals from the OCS. Insert the OCS through the panel cutout (from the front). The gasket must be between the host panel and the OCS.
5. Install and tighten the four mounting clips (provided in the box) until the gasket forms a tight seal. **NOTE:** Max torque is 0.8 to 1.13Nm, 7 to 10 in-lbs.
6. Reinstall the I/O Removable Terminal Blocks. Connect communications cables to the serial port, USB ports, Ethernet port, and CAN port as required.



# SAFETY & MAINTENANCE

## Warnings

1. To avoid the risk of electric shock or burns, always connect the safety (or earth) ground before making any other connections.
2. To reduce the risk of fire, electrical shock, or physical injury, it is strongly recommended to fuse the voltage measurement inputs. Be sure to locate fuses as close to the source as possible.
3. Replace fuse with the same type and rating to provide protection against risk of fire and shock hazards.
4. In the event of repeated failure, do NOT replace the fuse again as repeated failure indicates a defective condition that will NOT clear by replacing the fuse.
5. Only qualified electrical personnel familiar with the construction and operation of this equipment and the hazards involved should install, adjust, operate, or service this equipment.
6. Read and understand this manual and other applicable manuals in their entirety before proceeding. Failure to observe this precaution could result in severe bodily injury or loss of life.
7. **WARNING** - Battery may explode if mistreated. Do not recharge, disassemble, or dispose of in fire.
8. **WARNING - EXPLOSION HAZARD** - Batteries must only be changed in an area known to be non-hazardous.
9. **WARNING** - Do not disconnect while circuit is live unless are is know to be non-hazardous.

## FCC Compliance

This device complies with Part 15 of the FCC Rules. Operation is subject to the following

two conditions:

1. This device may not cause harmful interference.
2. This device must accept any interference received, including interference that may cause undesired operation.

## Technical Support

### North America

1 (317) 916-4274

(877) 665-5666

[www.hornerautomation.com](http://www.hornerautomation.com)

[techsppt@heapg.com](mailto:techsppt@heapg.com)

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[technical.support@horner-apg.com](mailto:technical.support@horner-apg.com)

## Precautions

All applicable codes and standards need to be followed in the installation of this product. Adhere to the following safety precautions whenever any type of connection is made to the module:

1. Connect the safety (earth) ground on the power connector first before making any
2. other connections.
3. When connecting to the electric circuits or pulse-initiating equipment, open their
4. related breakers.
5. Do NOT make connection to live power lines.
6. Make connections to the module first; then connect to the circuit to be monitored.
7. Route power wires in a safe manner in accordance with good practice and local codes.
8. Wear proper personal protective equipment including safety glasses and insulated gloves when making connections to power circuits.
9. Ensure hands, shoes, and floor are dry before making any connection to a power line.
10. Make sure the unit is turned OFF before making connection to terminals.
11. Make sure all circuits are de-energized before making connections.
12. Before each use, inspect all cables for breaks or cracks in the insulation. Replace
13. immediately if defective.
14. Use copper conductors in Field Wiring only, 60/75°C.
15. Use caution when connecting controllers to PCs via serial or USB. PCs, especially laptops, may use "floating power supplies" that are ungrounded. This could cause a damaging voltage potential between the laptop and controller. Ensure the controller and laptop are grounded for maximum protection. Consider using a USB isolator due to voltage potential differences as a preventative measure.