

# ***NPort***

## **Programmable Communication Gateway**

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### **API Reference**

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# MOXA PCG API Reference

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# Overview

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The purpose of this **Moxa PCG API Reference** is to give MOXA PCG (Programmable Communication Gateway) programmers a complete reference guide to the various function calls that are available. You may also refer to the companion guide, *MOXA Programmable Communication Gateway Programmer's Guide*. **API** stands for **Application Programming Interface**, which includes necessary function calls and linking libraries.



# Moxa API Quick Reference

The SDK API functions are displayed in the format shown below.

<b>Function Name</b>	<b>Brief function introduction</b>	<b>Function Attributes</b>
<b>Language Format</b>		
<b>Syntax</b>	<code>#include &lt;header file name&gt;</code>	
	<b>Function call</b>	
<b>Arguments</b>	<i>Variable names</i> Brief description of variables	
<b>Description</b>	Detailed function call description.	
<b>Return Value</b>	<b>Return Code #1</b> Description of return code	
	<b>Return Code #2</b> Description of return code	

To give you a specific example, we show here the function **sio\_oqueue**, which is from the SDK API Serial I/O library. This function reports the amount of data that is waiting to be transmitted out through the serial port.

<b>sio_oqueue</b>	<b>Get the length of data in both the system's output buffer and the driver's output buffer.</b>	<b>Port Status</b>
<b>C Format</b>		
<b>Syntax</b>	<code>#include &lt;sdksio.h&gt;</code>	
	<code>long sio_oqueue ( int port )</code>	
<b>Arguments</b>	<i>port</i> Async serial port number	
<b>Description</b>	Get the length of data not yet sent out in both the system's output buffer and the driver's output buffer.	
<b>Return Value</b>	<code>&gt;= 0</code> length of data (in bytes) still remaining in the driver's output buffer.	
	<code>SIO_BADPORT</code> Port was not open in advance.	

# SDK API Overview

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SDK stands for **Software Development Kit**, and includes not only the SDK APIs, but also SDK Utilities, the Windows utility used by the programmer to communicate with PCG, plus several detailed example programs. You may also refer to the companion guide, *MOXA Programmable Communication Gateway Programmer's Guide* for additional information about using the utility.

In order to make the SDK library easier to use, the function calls are divided into six groups, based on their attributes. The six groups are **Serial I/O API**, **BSD Socket API**, **Simplified Socket API**, **System Control API**, **Flash ROM Access API**, and **Debug API**.

By keeping these 6 groups of APIs in mind, programmers can more easily program the PCG to meet the needs of their application, and set up the PCG to operate as needed.

In this chapter, we give a brief introduction to all function calls for each of the six groups so that programmers can get a good overview of all of the APIs. For detailed usage of each API, refer to the following six sections:

- Serial I/O API Overview
- BSD Socket API Overview
- Simplified Socket API Overview
- System Control API Overview
- Flash ROM Access API Overview
- Debug API Overview

# Serial I/O API

In this section, we categorize the serial I/O library routines according to their function (**Port Control**, **Data Input**, **Data Output**, **Port Status Inquiry**, **Event Control**, and **Miscellaneous**). See Section 3-1 for a more detailed description of these functions.

You should also note you must include the header file **sdksio.h** in your source code that when calling these functions (see the example source code for details of how to include a header file).

<b>Port Control</b>	
This category includes functions to open serial ports, set communication parameters, and control signal lines.	
<b>Function Name</b>	<b>Description</b>
<b>sio_open</b>	Start receiving/transmitting data.
<b>sio_close</b>	Stop receiving/transmitting data.
<b>sio_ioctl</b>	Set port baud rate, parity, etc.
<b>sio_flowctrl</b>	Set port H/W and/or S/W flow control.
<b>sio_flush</b>	Flush input and/or output buffer.
<b>sio_DTR</b>	Set DTR state.
<b>sio_RTS</b>	Set RTS state.
<b>sio_lctrl</b>	Set both DTR and RTS states.
<b>sio_baud</b>	Set baud rate using the actual speed value.

<b>Data Input</b>	
This category includes functions to read data from the COM port.	
<b>Function Name</b>	<b>Description</b>
<b>sio_getch</b>	Read one character at a time from driver's input buffer.
<b>sio_read</b>	Read a block of data from the driver's input buffer.
<b>sio_SetReadTimeouts</b>	Set timeouts for sio_read().
<b>sio_GetReadTimeouts</b>	Get timeouts for sio_read().
<b>sio_AbortRead</b>	Abort when reading a block of data for sio_read().
<b>sio_linput</b>	Read a block of data ending with a termination character.

### Data Output

This category includes functions to write data to the serial port.

Function Name	Description
<a href="#">sio_putch</a>	Write one character at a time to driver's output buffer.
<a href="#">sio_write</a>	Write a block of data (probably only a partial block will be written).
<a href="#">sio_SetWriteTimeouts</a>	Set timeouts for <a href="#">sio_write()</a> .
<a href="#">sio_GetWriteTimeouts</a>	Get timeouts for <a href="#">sio_write()</a> .
<a href="#">sio_AbortWrite</a>	Abort when writing a block of data for <a href="#">sio_write()</a> .

### Port Status Inquiry

This category includes functions to query the communication status from the serial port.

Function Name	Description
<a href="#">sio_lstatus</a>	Get line status.
<a href="#">sio_iqueue</a>	Size of data accumulated in driver's input buffer.
<a href="#">sio_oqueue</a>	Size of data not yet sent out (still kept in driver's output buffer).
<a href="#">sio_Tx_hold</a>	Check why data could not be transmitted.
<a href="#">sio_getbaud</a>	Get the baud rate setting.
<a href="#">sio_getmode</a>	Get the settings for parity, data bits, etc.
<a href="#">sio_getflow</a>	Get the H/W and S/W flow control settings.
<a href="#">sio_data_status</a>	Check if errors occur when receiving data.

### Event Control

This category includes functions to set the communication event service routines for the serial port.

Function Name	Description
<a href="#">sio_term_irq</a>	Set event service routine when termination character is received.
<a href="#">sio_cnt_irq</a>	Set event service routine when a certain amount of data is received.
<a href="#">sio_modem_irq</a>	Set event service routine when line status is changed.
<a href="#">sio_break_irq</a>	Set event service routine when break signal is received.
<a href="#">sio_Tx_empty_irq</a>	Set event service routine when transmit buffer is empty.

<b>Miscellaneous</b>	
This category includes special COM port functions.	
<b>Function Name</b>	<b>Description</b>
<b>sio_break</b>	Send out BREAK signal.
<b>sio_break_ex</b>	Send out BREAK signal.
<b>sio_ActXon</b>	Causes transmission to act as if an XON character has been received.
<b>sio_ActXoff</b>	Causes transmission to act as if an XOFF character has been received.

## BSD Socket API

In this section, we categorize the BSD Socket library routines according to their function (**Socket Control**, **Data Input/Output**, **Socket Status Inquiry**, and **Miscellaneous**). See Section 3-2 for a more detailed description of these functions. You should also note that the header file **sdksock.h** must be included in your source code when calling these functions (see the example source code for details of how to include a header file).

<b>Socket Control</b>	
This category includes functions to open TCP sockets, and set and retrieve communication parameters.	
<b>Function Name</b>	<b>Description</b>
<b>accept</b>	An incoming connection is acknowledged and associated with an immediately created socket. The original socket is returned to the listening state.
<b>bind</b>	Assign a local name to an unnamed socket.
<b>closesocket</b>	Remove a socket from the per-process object reference table. Only blocks if SO_LINGER is set.
<b>connect</b>	Initiate a connection on the specified socket.
<b>ioctlsocket</b>	Provides control of sockets.
<b>listen</b>	Listen for incoming connections on a specified socket.
<b>setsockopt</b>	Store options associated with the specified socket.
<b>shutdown</b>	Shut down part of a full-duplex connection.
<b>socket</b>	Create an endpoint for communication and return a socket.
<b>getsockopt</b>	Retrieve options associated with the specified socket.

<b>Data Input/Output</b>	
This category includes functions to read/write data from the socket.	
<b>Function Name</b>	<b>Description</b>
<b>recv</b>	Receive data from a connected socket.
<b>recvfrom</b>	Receive data from either a connected or unconnected socket.
<b>select</b>	Perform synchronous I/O multiplexing.
<b>send</b>	Send data to a connected socket.
<b>sendto</b>	Send data to either a connected or unconnected socket.

<b>Socket Status Inquiry</b>	
This category includes functions to query the communication status from the socket.	
<b>Function Name</b>	<b>Description</b>
<b>getpeername</b>	Retrieve the name of the peer connected to the specified socket.
<b>getsockname</b>	Retrieve the current name for the specified socket.
<b>gethostname</b>	Retrieve the name of the local host.
<b>gethostbyname</b>	Retrieve the name(s) and address corresponding to a host name.

**Miscellaneous**

This category includes special socket functions.

<b>Function Name</b>	<b>Description</b>
<b>htonl</b>	Convert a 32-bit quantity from host byte order to network byte order.
<b>htons</b>	Convert a 16-bit quantity from host byte order to network byte order.
<b>inet_addr</b>	Convert a character string representing a number in the Internet standard "." notation to an Internet address value.
<b>inet_ntoa</b>	Convert an Internet address value to an ASCII string in "." notation (i.e., "a.b.c.d").
<b>ntohl</b>	Convert a 32-bit quantity from network byte order to host byte order.
<b>ntohs</b>	Convert a 16-bit quantity from network byte order to host byte order.

# Simplified Socket API

In this section, we categorize the Simplified Socket library routines according to their function (**Socket Control**, **Data Input/Output**, and **Socket Status Inquiry**). See Section 3-3 for a more detailed description of these functions.

You should also note that calling these functions requires that the header file **sdknet.h** must be included in your source code (see the example source code for details of how to include a header file).

<b>Socket Control</b>	
This category includes functions to open TCP sockets, and set and retrieve communication parameters.	
<b>Function Name</b>	<b>Description</b>
<b>tcp_open</b>	Open a local TCP port.
<b>tcp_close</b>	Close a local TCP port.
<b>tcp_connect</b>	Connect to specific host IP and port.
<b>tcp_listen</b>	Place a socket in a state where it is listening for an incoming connection.
<b>tcp_listento</b>	Listen for a specific incoming connection.
<b>tcp_connect_nowait</b>	Connect to a specific host IP and port no wait.
<b>tcp_listen_nowait</b>	Place a socket in a state where it is listening for an incoming connection no wait.
<b>tcp_listento_nowait</b>	Listen for a specific incoming connection no wait.
<b>udp_open</b>	Open a local UDP port.
<b>udp_close</b>	Close a local UDP port.



<b>Data Input/Output</b>	
This category includes functions to read/data from the socket.	
<b>Function Name</b>	<b>Description</b>
<a href="#">tcp_send</a>	Send data out through a connected socket.
<a href="#">tcp_rcv</a>	Receive data from a connected socket.
<a href="#">udp_send</a>	Send data to a specific destination.
<a href="#">udp_rcv</a>	Receive data from a specific source address.

<b>Socket Status Inquiry</b>	
This category includes functions to query the communication status of the socket.	
<b>Function Name</b>	<b>Description</b>
<a href="#">tcp_ofree</a>	Size of free space in the TCP driver's input buffer.
<a href="#">tcp_iqueue</a>	Get the size of data accumulated in the TCP driver's input buffer.
<a href="#">tcp_get_remote</a>	Get connected host IP and port.
<a href="#">tcp_state</a>	Get TCP state.
<a href="#">udp_ofree</a>	Size of free space in the UDP driver's input buffer.
<a href="#">udp_iqueue</a>	Get the size of data accumulated in the UDP driver's input buffer.

<b>Port Status Inquiry</b>	
This category includes functions to open TCP sockets, and set and retrieve communication parameters.	
<b>Function Name</b>	<b>Description</b>
<a href="#">net_get_IP</a>	Get local IP address.
<a href="#">net_get_netmask</a>	Get local subnet mask.
<a href="#">net_get_gateway</a>	Get local default gateway.
<a href="#">net_get_MAC_address</a>	Get MAC address.

# System Control API

This section presents the system information library routines, and gives a brief description of each routine. For a more detailed description of these routines, see Section 3-4.

You should also note that the header file **sdksys.h** must be included in your source code when calling these functions (see the example source code for details of how to include a header file).

Function Name	Description
<a href="#">sys_clock_s</a>	Read the server's time (in seconds), measured from power-up.
<a href="#">sys_clock_ms</a>	Read the server's time (in milliseconds) measured from power-up.
<a href="#">sys_sleep_ms</a>	Task sleep time (milliseconds).
<a href="#">sys_timeout</a>	Set the timeout event service routine.
<a href="#">sys_get_info</a>	Get server's general information.
<a href="#">sys_enable_watchdog</a>	Enable watchdog.
<a href="#">sys_disable_watchdog</a>	Disable watchdog.
<a href="#">sys_get_WatchdogStatus</a>	Get watchdog status.
<a href="#">sys_restart_system</a>	Restart system.
<a href="#">sys_restart_UserAP</a>	Restart user AP.
<a href="#">sys_set_RegisterID</a>	Set AP ID.
<a href="#">sys_get_SerialType</a>	Get current async port interface signal type.
<a href="#">sys_set_SerialType</a>	Set the async port interface signal type.
<a href="#">sys_event_suspend</a>	Suspend interrupt.
<a href="#">sys_event_resume</a>	Resume interrupt.
<a href="#">sys_exit</a>	Exit application.

# Flash ROM Access API

This section presents the Flash Library routines, and gives a brief description of each routine. For a more detailed description of these routines, see Section 3-5. You should also note that the header file **sdkflash.h** must be included in your source code when calling these functions (see the example source code for details of how to include a header file).

Function Name	Description
<b>flash_erase</b>	Erase flash-ROM.
<b>flash_length</b>	Get current data length in the flash-ROM.
<b>flash_write</b>	Write data to the flash-ROM.
<b>flash_read</b>	Read data from the flash-ROM.

# Debug API

This section presents the Debug Library routines, and gives a brief description of each routine. For a more detailed description of these routines, see Section 3-6. You should also note that the header file **sdkdbg.h** must be included in your source code when calling these functions (see the example source code for details of how to include a header file).

Function Name	Description
<b>dbg_put_ch()</b>	Print out a character for debugging.
<b>dbg_put_block()</b>	Print out a block of data for debugging.
<b>dbg_put_word()</b>	Print out a 2-byte unsigned integer value for debugging.
<b>dbg_put_doubleword()</b>	Print out a 4-byte unsigned long value for debugging.
<b>dbg_put_word_hex()</b>	Print out a 2-byte unsigned integer value with HEX format for debugging.
<b>dbg_put_doubleword_hex()</b>	Print out a 4-byte unsigned long value with HEX format for debugging.
<b>dbg_put_IP()</b>	Print out an IP address with the a.b.c.d format for debugging.
<b>dbg_put_string()</b>	Print out a string for debugging.

# SDK API Reference

---

## 3-1 Serial I/O Library Reference

**sio\_AbortRead** Abort when blocked from reading a block of data for `sio_read` and `sio_getch`. **Data Input**

---

**Syntax** `#include <sdksio.h>`

`int sio_AbortRead ( int port )`

**Arguments** *port* Async serial *port* number

**Description** Abort when blocked from reading a block of data for `sio_read` and `sio_getch`. Calling this function will cause `sio_read` to return immediately with return code of length of data read.

**Return Value** `SIO_OK` OK  
`SIO_BADPORT` Port was not open in advance.

**sio\_AbortWrite** Abort when blocked from writing a block of data for `sio_write` and `sio_putch`. **Data Output**

---

**Syntax** `#include <sdksio.h>`

`int sio_AbortWrite ( int port )`

**Arguments** *port* Async serial *port* number

**Description** Abort when blocked from writing a block of data for `sio_write()` or `sio_putch()`. Calling this function will cause `sio_write()` to return immediately with return code `SIO_ABORT_WRITE`.

**Return Value** `SIO_OK` OK  
`SIO_BADPORT` Port was not already open

**sio\_ActXoff**                      **This function causes transmission to act as if an XOFF character has been received.**                      **Misc.**

---

**Syntax**                      **#include <sdksio.h>**  
**int sio\_ActXoff ( int port )**

**Arguments**                      *port*    Async serial port number

**Description**                      This function causes transmission to act as if an XOFF character has been received.

**Return Value**                      SIO\_OK                      OK  
SIO\_BADPORT                      Port was not open in advance.

**sio\_Act\_Xon**                      **This function causes transmission to act as if an XON character has been received.**                      **Misc.**

---

**Syntax**                      **#include <sdksio.h>**  
**int sio\_ActXon ( int port )**

**Arguments**                      *port*    Async serial port number

**Description**                      This function causes transmission to act as if an XON character has been received.

**Return Value**                      SIO\_OK                      OK  
SIO\_BADPORT                      Port was not open in advance.

**sio\_baud**                      **Set baud rate using the actual speed value.**                      **Port Control**

---

**Syntax**                      **#include <sdksio.h>**  
**int sio\_baud ( int port, long speed )**

**Arguments**                      *port*    Async serial port number  
*speed*    true baud rate: e.g., 200, 1200, 9600, 19200

**Description**                      Set baud rate using the actual speed value.

**Return Value**                      SIO\_OK                      OK  
SIO\_BADPORT                      Port was not open in advance.

<b>sio_break</b>	<b>Send out a break signal.</b>	<b>Misc.</b>
<b>Syntax</b>	<code>#include &lt;sdksio.h&gt;</code> <code>int sio_break ( int port, int time )</code>	
<b>Arguments</b>	<i>port</i> Async serial port number <i>time</i> break time in tics (1/18.2 second)	
<b>Description</b>	This function will block until the time has expired.	
<b>Return Value</b>	SIO_OK OK SIO_BADPORT Port was not open in advance. SIO_BADPARAM Bad parameter	
<b>sio_break_ex</b>	<b>Send out a break signal.</b>	<b>Misc.</b>
<b>Syntax</b>	<code>#include &lt;sdksio.h&gt;</code> <code>int sio_break_ex ( int port, int ms )</code>	
<b>Arguments</b>	<i>port</i> Async serial port number <i>ms</i> break time in milliseconds	
<b>Description</b>	Sends out a break signal. This function will block transmission until the time has expired, and is the same as <code>sio_break()</code> , except that the time unit is measured in milliseconds.	
<b>Return Value</b>	SIO_OK OK SIO_BADPORT Port was not open in advance. SIO_BADPARAM Bad parameter.	
<b>sio_break_irq</b>	<b>Set an event service routine for the case when a BREAK signal is received.</b>	<b>Event Control</b>
<b>Syntax</b>	<code>#include &lt;sdksio.h&gt;</code> <code>int sio_break_irq ( int port, void (*func) (int port) )</code>	
<b>Arguments</b>	<i>port</i> Async serial port number <i>func</i> event service routine entry If <i>func</i> is NULL, this routine will be disabled.	
<b>Description</b>	Set an event service routine for the case when a BREAK signal is received. When a BREAK signal is encountered, the system will call the event service routine.	
<b>Return Value</b>	SIO_OK OK SIO_BADPORT Port was not open in advance.	

<code>sio_close</code>	Disable a serial port.	Port Control
<b>Syntax</b>	<code>#include &lt;sdksio.h&gt;</code> <code>int sio_close ( int port )</code>	
<b>Arguments</b>	<i>port</i> Async serial port number	
<b>Description</b>	Disable a serial port so that it cannot receive/transmit data.	
<b>Return Value</b>	SIO_OK	OK
	SIO_BADPORT	Port was not open in advance.

<code>sio_cnt_irq</code>	Set an event service routine for the case when a certain amount of data has been received.	Event Control
<b>Syntax</b>	<code>#include &lt;sdksio.h&gt;</code> <code>int sio_cnt_irq ( int port, void (*func) (int port), int count )</code>	
<b>Arguments</b>	<i>port</i> Async serial port number <i>func</i> event service routine entry If <i>func</i> is NULL, this routine will be disabled. <i>count</i> data count	
<b>Description</b>	Set an event service routine for the case when a certain amount of data has been received. When there are 'count' bytes of data received in the input buffer, the system will call the event service routine.	
<b>Return Value</b>	SIO_OK	OK
	SIO_BADPORT	Port was not open in advance.

**sio\_data\_status**      **Check if an error occurred when receiving data.**      **Port Status**

---

**Syntax**      **#include <sdksio.h>**  
**int sio\_data\_status ( int port )**

**Arguments**      *port* Async serial port number

**Description**      Check if an error occurred when receiving data.

**Return Value**      = 0 no error occurred  
> 0 bit 0 on - parity error  
                         bit 1 on - framing error  
                         bit 2 on - overrun error  
                         bit 3 on - overflow error

SIO\_BADPORT      Port was not open in advance.

**sio\_DTR**      **Set the DTR state of a port.**      **Port Control**

---

**Syntax**      **#include <sdksio.h>**  
**int sio\_DTR ( int port, int mode )**

**Arguments**      *port* Async serial port number  
*mode* 0: Turn DTR off  
                         1: Turn DTR on

**Description**      Set the DTR state of a port.

**Return Value**      SIO\_OK      OK  
                         SIO\_BADPORT      Port was not open in advance.  
                         SIO\_BADPARAM      Bad parameter



**sio\_flowctrl**                      **Set hardware and/or software flow control.**                      **Port Control**

---

**Syntax**                      **#include <sdksio.h>**  
**int sio\_flowctrl ( int port, int mode )**

**Arguments**                      *port*      Async serial port number  
*mode*      bit 0:      CTS flow control  
                 bit 1:      RTS flow control  
                 bit 2:      Tx XON/XOFF flow control  
                 bit 3:      Rx XON/XOFF flow control  
                 (0 = OFF, 1 = ON)

**Description**                      Set the hardware and/or software flow control.

**Return Value**                      SIO\_OK                      OK  
   SIO\_BADPORT                      Port was not open in advance.  
   SIO\_BADPARAM                      Bad parameter

**sio\_flush**                      **Flush the driver's input/output buffer.**                      **Port Control**

---

**Syntax**                      **#include <sdksio.h>**  
**int sio\_flush ( int port, int func )**

**Arguments**                      *port*      Async serial port number  
*func*      flush action  
                 0:      flush input buffer  
                 1:      flush output buffer  
                 2:      flush input & output buffer

**Description**                      Flush the driver's input/output buffer. The data will no longer exist.

**Return Value**                      SIO\_OK                      OK  
   SIO\_BADPORT                      Port was not open in advance.  
   SIO\_BADPARAM                      Bad parameter

---

<b>sio_getbaud</b>	<b>Get the serial port's baud rate setting.</b>	<b>Port Status</b>
--------------------	---	--------------------

---

<b>Syntax</b>	<code>#include &lt;sdksio.h&gt;</code> <code>long sio_getbaud ( int port )</code>
<b>Arguments</b>	<i>port</i> Async serial port number
<b>Description</b>	Get the serial port's baud rate setting. The return value is the actual baud rate. For example, a return value of 9600 means 9600 bps whereas 200 means 200 bps.
<b>Return Value</b>	> 0 the actual baud rate SIO_BADPORT Port was not open in advance.

---

<b>sio_getch</b>	<b>Read one character from the driver's input buffer.</b>	<b>Data Input</b>
------------------	---	-------------------

---

<b>Syntax</b>	<code>#include &lt;sdksio.h&gt;</code> <code>int sio_getch ( int port )</code>
<b>Arguments</b>	<i>port</i> Async serial port number
<b>Description</b>	Read one character from the driver's input buffer.
<b>Return Value</b>	0 to 255 The ASCII code of the character received. SIO_BADPORT Port was not open in advance.  SIO_NODATA No data to read. SIO_BADPARAM Bad parameter.

---

<b>sio_getflow</b>	<b>Get the serial port's hardware and software flow control settings.</b>	<b>Port Status</b>
--------------------	---	--------------------

---

<b>Syntax</b>	<code>#include &lt;sdksio.h&gt;</code> <code>int sio_getflow ( int port )</code>
<b>Arguments</b>	<i>port</i> Async serial port number
<b>Description</b>	Get the serial port's hardware and software flow control settings. See the sio_flowctrl() function.
<b>Return Value</b>	>=0 bit 0 = 1 CTS flow contro bit 1 = RTS flow control bit 2 = Tx XON/XOFF flow control bit 3 = Rx XON/XOFF flow control SIO_BADPORT Port was not open in advance.

<b>sio_getmode</b>	<b>Get the serial port's mode settings.</b>	<b>Port Status</b>
<b>Syntax</b>	<code>#include &lt;sdksio.h&gt;</code> <code>int sio_getmode ( int port )</code>	
<b>Arguments</b>	<i>port</i> Async serial port number	
<b>Description</b>	Get the serial port's mode settings. Refer to the description of sio_ioctl() to see the mode settings.	
<b>Return Value</b>	>=0 mode (see sio_ioctl()) SIO_BADPORT Port was not open in advance.	

<b>sio_GetReadTimeouts</b>	<b>Get timeout values for sio_read and sio_getch.</b>	<b>Data Input</b>
<b>Syntax</b>	<code>#include &lt;sdksio.h&gt;</code> <code>int sio_GetReadTimeouts ( int port, DWORD *TotalTimeouts, DWORD *IntervalTimeouts )</code>	
<b>Arguments</b>	<i>port</i> Async serial port number <i>TotalTimeouts</i> Total timeout values <i>IntervalTimeouts</i> Interval timeout values	
<b>Description</b>	Get timeout values for sio_read and sio_getch.	
<b>Return Value</b>	SIO_OK OK SIO_BADPORT Port was not open in advance.	

<b>sio_GetWriteTimeouts</b>	<b>Get timeout values for sio_write and sio_putch.</b>	<b>Data Output</b>
<b>Syntax</b>	<code>#include &lt;sdksio.h&gt;</code> <code>int sio_GetWriteTimeouts ( int port, DWORD *TotalTimeouts )</code>	
<b>Arguments</b>	<i>port</i> Async serial port number <i>TotalTimeouts</i> Total timeout values	
<b>Description</b>	Get timeout values for sio_write() and sio_putch().	
<b>Return Value</b>	SIO_OK OK SIO_BADPORT Port was not already open	

<b>sio_ioctl</b>	<b>Control the settings of the serial port's I/O control register.</b>	<b>Port Control</b>
------------------	--	---------------------

**Syntax****#include <sdksio.h>****int sio\_ioctl ( int port, int baud, int mode )****Arguments**

*port* Async serial port number

*baud* (bits/sec)

0 = 50	6 = 600	12 = 9600
1 = 75	7 = 1200	13 = 19200
2 = 110	8 = 1800	14 = 38400
3 = 134.5	9 = 2400	15 = 57600
4 = 150	10 = 4800	16 = 115200
5 = 300	11 = 7200	17 = 230400

*mode* bit\_cnt OR stop\_bit OR parity

bit\_cnt (bits 0, 1) =

0x00 = bit_5
0x01 = bit_6
0x02 = bit_7
0x03 = bit_8

stop\_bit (bit 2) =

0x00 = stop_1
0x04 = stop_2

parity (bits 3,4 5) =

0x00 = none
0x08 = odd
0x18 = even
0x28 = mark
0x38 = space

**Description**

Control the settings of the serial port's I/O control register, such as baud rate, parity, data bits, and stop bit.

**Return Value**

SIO_OK	OK
SIO_BADPORT	Port was not open in advance.
SIO_BADPARAM	Bad parameter

**sio\_iqueue**                      **Get the size of data accumulated in the system's input buffer and driver's input buffer.**                      **Port Status**

---

**Syntax**                      **#include <sdksio.h>**  
**long sio\_iqueue ( int port )**

**Arguments**                      *port*                      Async serial port number

**Description**                      Get the size of data accumulated in the system's input buffer and driver's input buffer. (User must be aware of the fact that there may be a few characters still in the RS-232 UART chip and not yet known when sio\_iqueue() returns a zero value.)

**Return Value**                      >= 0                      data in input buffer (bytes)  
SIO\_BADPORT                      Port was not open in advance.

**sio\_lctrl**                      **Set both the DTR and RTS states.**                      **Port Control**

---

**Syntax**                      **#include <sdksio.h>**  
**int sio\_lctrl ( int port, int mode )**

**Arguments**                      *port*                      Async serial port number  
*mode*                      C\_DTR (bit 0)                      C\_RTS (bit 1)

**Description**                      Set both the DTR and RTS states.

**Return Value**                      SIO\_OK                      OK  
SIO\_BADPORT                      Port was not open in advance.  
SIO\_BADPARAM                      Bad parameter

**sio\_linput**                      **Read a block of data from the driver's input buffer .**                      **Data Input**

---

**Syntax**                      **#include <sdksio.h>**  
**int sio\_linput ( int port, char \*buf, int len, int term )**

**Arguments**                      *port*      Async serial port number  
   *buf*        receive buffer pointer  
   *len*        buffer length  
   *term*      terminator code

**Description**                      Read a block of data from the driver's input buffer until the terminator character is encountered or "len" bytes of data are read.

**Return Value**                      > 0                      length of data received  
   = 0                      no data received  
   SIO\_BADPORT          Port was not open in advance.  
   SIO\_BADPARAM        Bad parameter.

**sio\_lstatus**                      **Get the status of the line.**                      **Port Status**

---

**Syntax**                      **#include <sdksio.h>**  
**int sio\_lstatus ( int port )**

**Arguments**                      *port*      Async serial port number

**Description**                      Get the status of the line.

**Return Value**                      >= 0                      line status  
                        Bit 0 – S\_CTS  
                        Bit 1 – S\_DSR  
                        Bit 2 – S\_RI  
                        Bit 3 – S\_CD  
   SIO\_BADPORT          Port was not open in advance.

**sio\_modem\_irq**      **Set an event service routine for the case when the line status is changed.**      **Event Control**

---

**Syntax**      **#include <sdksio.h>**  
**int sio\_modem\_irq ( int port, void (\*func) (int port) )**

**Arguments**      *port*      Async serial port number  
*func*      event service routine entry

If the *func* is NULL, it will disable this routine.

**Description**      Set an event service routine for the case when the line status has changed. When line status (CTS, DSR, CD, RI) changes, the system will call the event service routine.

**Return Value**      SIO\_OK      OK  
SIO\_BADPORT      Port was not open in advance.

**sio\_ofree**      **Get the length of free space in the driver's output buffer.**      **Port Status**

---

**Syntax**      **#include <sdksio.h>**  
**long sio\_ofree ( int port )**

**Arguments**      *port*      Async serial port number

**Description**      Get the length of free space in the driver's output buffer.

**Return Value**      >= 0      free space in output buffer (bytes)  
SIO\_BADPORT      Port was not open in advance.

**sio\_open**      **Enable a serial port for data transmitting/receiving.**      **Port Control**

---

**Syntax**      **#include <sdksio.h>**  
**int sio\_open ( int port )**

**Arguments**      *port*      Async serial port number for NPort-4511 is always 1.

**Description**      Enable a serial port for data transmitting/receiving. After calling *sio\_open*, the initial status of this COM port is the same as the last setting or configuration setting.

**Return Value**      >= 0      Open action was successful, and this return value is a descriptor referencing the port. The programmer can use this descriptor in the *select()* function (from the socket API group) to carry out a data read/write operation.  
SIO\_BADPORT      Port number is invalid.

**sio\_oqueue**                      **Get the length of data not yet sent out in both the system's output buffer and the driver's output buffer.**                      **Port Status**

---

**Syntax**                      **#include <sdksio.h>**  
**long sio\_oqueue ( int port )**

**Arguments**                      *port*      Async serial port number

**Description**                      Get the length of data not yet sent out in both the system's output buffer and the driver's output buffer.

**Return Value**                      >= 0      length of data (in bytes) still remaining in the driver's output buffer.  
SIO\_BADPORT                      Port was not open in advance.

**sio\_putch**                      **Write a character into the driver's output buffer.**                      **Data Output**

---

**Syntax**                      **#include <sdksio.h>**  
**int sio\_putch ( int port, int term )**

**Arguments**                      *port*      Async serial port number  
*term*      character (0 - 255)

**Description**                      Write a character into the driver's output buffer.

**Return Value**                      SIO\_OK                      OK  
SIO\_BADPORT                      Port was not already open  
SIO\_BADPARAM                      Bad parameter  
SIO\_ABORT\_WRITE                      User abort blocked write  
SIO\_WRITETIMEOUT                      Write timeout has occurred



---

**sio\_read**                      **Read data from the driver's input buffer**                      **Data Input**

---

**Syntax**                      `#include <sdksio.h>`  
`int sio_read ( int port, char *buf, int len )`

**Arguments**                      *port*                      Async serial port number  
*buf*                      receive buffer pointer  
*len*                      buffer length

**Description**                      Read data from the driver's input buffer. If the length of data in the driver's input buffer is less than the user's buffer, then all data in the driver's input buffer will be transferred to the user's buffer. Otherwise, only 'len' bytes will be transferred to the user's buffer.

`sio_set_ReadTimeout()` can be used to set timeouts for `sio_read`.

`sio_AbortRead()` can be used to abort any blocked `sio_read`.

**Return Value**                      > 0                      length of data received  
   = 0                      no data received  
   SIO\_BADPORT                      Port was not open in advance.  
   SIO\_BADPARAM                      Bad parameter.

---

**sio\_RTS**                      **Set the RTS state of a port.**                      **Port Control**

---

**Syntax**                      `#include <sdksio.h>`  
`int sio_RTS ( int port, int mode )`

**Arguments**                      *port*                      Async serial port number  
*mode*                      0: Turn RTS off  
   1: Turn RTS on

**Description**                      Set the RTS state of a port.

**Return Value**                      SIO\_OK                      OK  
   SIO\_BADPORT                      Port was not open in advance.  
   SIO\_BADPARAM                      Bad parameter.  
   SIO\_RTS\_BY\_HW                      Can't control the port because it is set as auto H/W flow control by `sio_flowctrl()`.

<b>sio_SetReadTimeouts</b>	<b>Set timeout values for sio_read and sio_getch.</b>	<b>Data Input</b>
<b>Syntax</b>	<b>#include &lt;sdksio.h&gt;</b> <b>int sio_SetReadTimeouts ( int <i>port</i>, DWORD <i>TotalTimeouts</i>, DWORD <i>IntervalTimeouts</i> )</b>	
<b>Arguments</b>	<i>port</i>	Async serial port number
	<i>TotalTimeouts</i>	Total timeout values
	<i>IntervalTimeouts</i>	Interval timeout values
<b>Description</b>	Set timeout values for sio_read and sio_getch. The default <i>TotalTimeouts</i> value is MAXDWORD and the <i>IntervalTimeouts</i> value is 0, which enables sio_read to return immediately.	
<b>Return Value</b>	SIO_OK	OK
	SIO_BADPORT	Port was not open in advance.

<b>sio_SetWriteTimeouts</b>	<b>Set timeout values for sio_write and sio_putch.</b>	<b>Data Output</b>
<b>Syntax</b>	<b>#include &lt;sdksio.h&gt;</b> <b>int sio_SetWriteTimeouts ( int <i>port</i>, DWORD <i>TotalTimeouts</i> )</b>	
<b>Arguments</b>	<i>port</i>	Async serial port number
	<i>TotalTimeouts</i>	Total timeout values
<b>Description</b>	Set timeout values for sio_write() and sio_putch(). The default value is 0, which enables sio_write() to always block until it is finished writing data.	
	The value 0xFFFFFFFF enables sio_write() and sio_putch() to return immediately without blocking at all.	
	The value 0 enables sio_write() to always block until finished writing data.	
<b>Return Value</b>	SIO_OK	OK
	SIO_BADPORT	Port was not already open
	SIO_BADPARAM	Bad parameter

**sio\_term\_irq**                      **Set an event service routine for the case when the terminator character is received.**                      **Event Control**

---

**Syntax**                      `#include <sdksio.h>`  
`int sio_term_irq ( int port, void (*func) (int port), char code )`

**Arguments**                      *port*      Async serial port number  
*func*      event service routine entry  
If the *func* is NULL, it will disable this routine.  
*code*      terminator code

**Description**                      Set an event service routine for the case when the terminator character is received. When the terminator character is received, the system will call the event service routine.

**Return Value**                      SIO\_OK                      OK  
SIO\_BADPORT                      Port was not open in advance.

**sio\_Tx\_empty\_irq**                      **Set an event service routine for the case when the last character in the output buffer was sent.**                      **Event Control**

---

**Syntax**                      `#include <sdksio.h>`  
`int sio_Tx_empty_irq ( int port, void (*func) (int port) )`

**Arguments**                      *port*      Async serial port number  
*func*      event service routine entry  
If the *func* is NULL, it will disable this routine

**Description**                      Set an event service routine for the case when the last character in the output buffer was sent. When the Tx empty signal is encountered, the system will call the event service routine.

**Return Value**                      SIO\_OK                      OK  
SIO\_BADPORT                      Port was not open in advance.

<b>sio_Tx_hold</b>	<b>Check why data could not be transmitted.</b>	<b>Port Status</b>
--------------------	---	--------------------

---

<b>Syntax</b>	<b>#include &lt;sdksio.h&gt;</b>	
	<b>int sio_Tx_hold ( int port )</b>	
<b>Arguments</b>	<i>port</i> Async serial port number	
<b>Description</b>	Check the reason why data could not be transmitted.	
<b>Return Value</b>	>=0     bit 0 on; could not transmit data because CTS is low bit 1 on; could not transmit data because XOFF char received SIO_BADPORT     Port was not open in advance.	

<b>sio_write</b>	<b>Write a block of data to the driver's output buffer.</b>	<b>Data Output</b>
------------------	---	--------------------

---

<b>Syntax</b>	<b>#include &lt;sdksio.h&gt;</b>	
	<b>int sio_write ( int port, char *buf, int len )</b>	
<b>Arguments</b>	<i>port</i> Async serial port number	
	<i>buf</i> transmit string pointer	
	<i>len</i> transmit string length	
<b>Description</b>	Write a block of data to the driver's output buffer. The actual length of data written depends on the amount of free space in the driver's output buffer. sio_write() is always non-block by default. sio_set_WriteTimeout() can be used to set timeouts for sio_write(). SIO_WRITETIMEOUT will be returned for sio_write() when write timeouts. sio_abort_write() can be used to abort any blocked sio_write() with return value SIO_ABORT_WRITE.	
<b>Return Value</b>	>= 0     length of data transmitted SIO_BADPORT     Port was not already open SIO_BADPARAM     Bad parameter SIO_ABORT_WRITE     User abort blocked write SIO_WRITETIMEOUT     Write timeout has occurred	

## 3-2 BSD Socket Library Reference

<b>accept</b>	<b>Accept a connection on a socket.</b>
<b>Syntax</b>	<pre>#include &lt;sdksoc.h&gt; int accept ( int s, SOCKADDR *addr, int *addrlen );</pre>
<b>Arguments</b>	<p><i>s</i> A descriptor identifying a socket which is listening for connections after a listen().</p> <p><i>addr</i> An optional pointer to a buffer that receives the address of the connecting entity, as known to the communications layer. The exact format of the <i>addr</i> argument is determined by the address family established when the socket was created.</p> <p><i>addrlen</i> An optional pointer to an integer that contains the length of the address <i>addr</i>.</p>
<b>Description</b>	<p>This routine extracts the first connection on the queue of pending connections on <i>s</i>, creates a new socket with the same properties as <i>s</i> and returns a handle to the new socket. If no pending connections are present on the queue, and the socket is not marked as non-blocking, <code>accept()</code> blocks the caller until a connection is present. If the socket is marked non-blocking and no pending connections are present on the queue, <code>accept()</code> returns an error as described below. The accepted socket may not be used to accept more connections. The original socket remains open.</p> <p>The argument <i>addr</i> is a result parameter that is filled in with the address of the connecting entity, as known to the communications layer. The exact format of the <i>addr</i> parameter is determined by the address family in which the communication is occurring. The <i>addrlen</i> is a value-result parameter; it should initially contain the amount of space pointed to by <i>addr</i>; on return it will contain the actual length (in bytes) of the address returned. This call is used with connection-based socket types such as <code>SOCK_STREAM</code>. If <i>addr</i> and/or <i>addrlen</i> are equal to <code>NULL</code>, then no information about the remote address of the accepted socket is returned.</p>

**Return Value** If no error occurs, `accept()` returns a value of type `int` which is a descriptor for the accepted packet. Otherwise, a value of `-1` is returned, and the global variable `errno` contains one of the following values. The integer referred to by `addrlen` initially contains the amount of space pointed to by `addr`. On return it will contain the actual length in bytes of the address returned.

<b>Error Codes</b>	EBADF	The first argument does not specify a valid descriptor.
	EOPNOTSUPP	The socket is not of type <code>SOCK_STREAM</code> .
	EFAULT	The pointer in argument is invalid.
	EWOULDBLOCK	The socket is marked non-blocking and no connections are waiting to be accepted.
	EFILE	The initial system file table is full.

**See Also** `bind()`, `connect()`, `listen()`, `select()`, `socket()`  
**Warnings**

## **`bind`** Associate a local address with a socket.

---

<b>Syntax</b>	<code>#include &lt;sdksoc.h&gt;</code> <code>int bind ( int s, SOCKADDR *name, int namelen );</code>
<b>Arguments</b>	<code>s</code> A descriptor identifying an unbound socket <code>name</code> The address to assign to the socket. <code>namelen</code> The length of the name.
<b>Description</b>	This routine is used on an unconnected datagram or stream socket, before subsequent <code>connect()</code> 's or <code>listen()</code> 's. When a socket is created with <code>socket()</code> , it exists in a name space (address family), but it has no name assigned. <code>bind()</code> establishes the local association (host address/port number) of the socket by assigning a local name to an unnamed socket.

In the Internet address family, a name consists of several components. For SOCK\_DGRAM and SOCK\_STREAM, the name consists of three parts: a host address, the protocol number (set implicitly to UDP or TCP, respectively), and a port number which identifies the application. If an application does not care what address is assigned to it, it may specify an Internet address equal to INADDR\_ANY, a port equal to 0, or both. If the Internet address is equal to INADDR\_ANY, any appropriate network interface will be used; this simplifies application programming in the presence of multi-homed hosts. If the port is specified as 0, the Windows Sockets implementation will assign a unique port to the application with a value between 1024 and 30000. The application may use getsockname() after bind() to learn the address that has been assigned to it, but note that getsockname() will not necessarily fill in the Internet address until the socket is connected, since several Internet addresses may be valid if the host is multi-homed.

**Return Value**

If no error occurs, bind() returns 0. Otherwise, it returns -1, and the global variable *errno* contains one of the following values.

**Error Codes**

- EFAULT     The *namelen* argument is too small (less than the size of a SOCKADDR) or the name argument pointer is invalid.
- EINVAL     The socket is already bound to an address.
- EBADF     The descriptor is not a socket.

**See Also**

connect(), listen(), getsockname(), setsockopt(), socket().

## closesocket

Close a socket.

---

### Syntax

```
#include <sdksoc.h>
```

```
int closesocket ( int s );
```

### Arguments

*s* A descriptor identifying a socket.

### Description

This function closes a socket. More precisely, it releases the socket descriptor *s*, so that further references to *s* will fail with the error EBADF. If this is the last reference to the underlying socket, the associated naming information and queued data are discarded.

The semantics of closesocket() are affected by the socket options SO\_LINGER and SO\_DONTLINGER as follows:

Option	Interval	Type of close	Wait for close?
SO_DONTLINGER	Don't care	Graceful	No
SO_LINGER	Zero	Hard	No
SO_LINGER	Non-zero	Graceful	Yes

If SO\_LINGER is set (i.e., the *l\_onoff* field of the linger structure is non-zero) with a zero timeout interval (*l\_linger* is zero), closesocket() is not blocked even if queued data has not yet been sent or acknowledged. This is called a "hard" or "abortive" close, because the socket's virtual circuit is reset immediately, and any unsent data is lost.

If SO\_LINGER is set with a non-zero timeout interval, the closesocket() call blocks until the remaining data has been sent or until the timeout expires. This is called a graceful disconnect.



If `SO_DONTLINGER` is set on a stream socket (i.e. the `l_onoff` field of the `linger` structure is zero), the `closesocket()` call will return immediately. However, any data queued for transmission will be sent if possible before the underlying socket is closed. This is also called a graceful disconnect. Note that in this case the Windows Sockets implementation may not release the socket and other resources for an arbitrary period, which may affect applications which expect to use all available sockets.

**Return Value**

If no error occurs, `closesocket()` returns 0. Otherwise, it returns -1, and the global variable `errno` contains one of the following values.

**Error Codes**

`EBADF` The descriptor is not a socket.

**See Also**

`accept()`, `socket()`, `ioctlsocket()`, `setsockopt()`.

**connect**

**Establish a connection to a peer.**

---

**Syntax**

```
#include <sock.h>
int connect ( int s, SOCKADDR *name, int
namelen );
```

**Arguments**

*s* A descriptor identifying an unconnected socket.

*name* The name of the peer to which the socket is to be connected.

*namelen* The length of the *name*.

**Description**

This function is used to create a connection to the specified foreign association. The parameter *s* specifies an unconnected datagram or stream socket. If the socket is unbound, unique values are assigned to the local association by the system, and the socket is marked as bound. Note that if the address field of the *name* structure is all zeroes, `connect()` will return the error `EADDRNOTAVAIL`.

For stream sockets (type `SOCK_STREAM`), an active connection is initiated to the foreign host using *name* (an address in the name space of the socket). When the socket call completes successfully, the socket is ready to send/receive data.

For a datagram socket (type `SOCK_DGRAM`), a default destination is set, which will be used on subsequent `send()` and `recv()` calls.

**Return Value**

If no error occurs, connect() returns 0. Otherwise, it returns -1, and the global variable *errno* contains one of the following values.

On a blocking socket, the return value indicates success or failure of the connection attempt.

On a non-blocking socket, if the return value is -1 an application should check the *errno*. If this indicates an error code of EINPROGRESS, then your application can use select() to determine the completion of the connection request by checking if the socket is writeable.

**Error Codes**

EINPROGRESS	(TCP only) The socket is nonblocking and a connection attempt would block.
EADDRNOTAVAIL	The specified address is not available
EADDRINUSE	The specified address already in use
ECONNREFUSED	(TCP only) The attempt to connect was forcefully rejected by the remote machine.
EISCONN	The socket is already connected.
EBADF	The descriptor is not a socket.
ETIMEDOUT	(TCP only) Attempt to connect timed out without establishing a connection. Current time out value is 30 seconds.

**See Also**

accept(), bind(), getsockname(), socket(), select().

## **gethostbyname**      **Get host information corresponding to a hostname.**

---

### **Syntax**

```
#include <sdksock.h>
```

```
struct hostent *gethostbyname ( char *name );
```

### **Arguments**

*name*      A pointer to the name of the host.

### **Description**

gethostbyname() returns a pointer to the following structure which contains the name(s) and address which correspond to the given address.

```
struct hostent {  
    char *      h_name;  
    char **     h_aliases;  
    short      h_addrtype;  
    short      h_length;  
    char * *    h_addr_list;  
};
```

The members of this structure are:

Element	Usage
<i>h_name</i>	server name of local system
<i>h_aliases</i>	A NULL-terminated array of alternate names, unused currently.
<i>h_addrtype</i>	The type of address being returned; this is always AF_INET.
<i>h_length</i>	The length, in bytes, this is always 4
<i>h_addr_list</i>	A NULL-terminated list of addresses for the host. Addresses are returned in network byte order.

The pointer returned points to a structure that is allocated by NPort Server. The application must not modify this structure or free any of its components.

### **Return Value**

If no error occurs, gethostbyname() returns a pointer to the hostent structure described above. Otherwise it returns a NULL pointer.

### **See Also**

gethostname()

---

**gethostname**      **Return the standard host name for the local machine.**

---

<b>Syntax</b>	<pre>#include &lt;sdksock.h&gt; int  gethostname ( char *name, int namelen );</pre>
<b>Arguments</b>	<p><i>name</i>      A pointer to a buffer that will receive the host name.</p> <p><i>namelen</i>    The length of the buffer.</p>
<b>Description</b>	This routine returns the name of the local host into the buffer specified by the <i>name</i> parameter. The host name is returned as a null-terminated string. The form of the host name is dependent on the sockets implementation—it is a simple host name. However, it is guaranteed that the name returned will be successfully parsed by <code>gethostbyname()</code> .
<b>Return Value</b>	If no error occurs, <code>gethostname()</code> returns 0. Otherwise, it returns -1, and the global variable <i>errno</i> contains one of the following values.
<b>Error Codes</b>	WSAEFAULT    The <i>namelen</i> parameter is too small or the name argument pointer is invalid.
<b>See Also</b>	<code>gethostbyname()</code>

---

**getpeername**      **Get the address of the peer to which a socket is connected.**

---

<b>Syntax</b>	<pre>#include &lt;sdksock.h&gt; int  getpeername ( int s, SOCKADDR *name, int *namelen );</pre>
<b>Arguments</b>	<p><i>s</i>      A descriptor identifying a connected socket.</p> <p><i>name</i>    The structure which is to receive the name of the peer.</p> <p><i>namelen</i>    A pointer to the size of the name structure.</p>
<b>Description</b>	<code>getpeername()</code> retrieves the name of the peer connected to the socket <i>s</i> and stores it in the SOCKADDR identified by <i>name</i> . It is used on a connected datagram or stream socket.
	On return, the <i>namelen</i> argument contains the actual size of the name returned in bytes.

<b>Return Value</b>	If no error occurs, <code>getpeername()</code> returns 0. Otherwise, it returns <code>-1</code> , and the global variable <code>errno</code> contains one of the following values.	
<b>Error Codes</b>	<code>EFAULT</code>	The <i>name</i> argument pointer is invalid or <i>namelen</i> argument is not large enough.
	<code>ENOTCONN</code>	The socket is not connected.
	<code>EBADF</code>	The descriptor is not a socket.
<b>See Also</b>	<code>bind()</code> , <code>socket()</code> , <code>getsockname()</code> .	

### getsockname      **Get the local name for a socket.**

---

<b>Syntax</b>	<code>#include &lt;sock.h&gt;</code> <code>int getsockname ( int s, SOCKADDR *name, int *namelen );</code>	
<b>Arguments</b>	<i>s</i>	A descriptor identifying a bound socket.
	<i>name</i>	Receives the address (name) of the socket.
	<i>namelen</i>	The size of the <i>name</i> buffer.
<b>Description</b>	<code>getsockname()</code> retrieves the current name for the specified socket descriptor in <i>name</i> . It is used on a bound and/or connected socket specified by the <i>s</i> parameter. The local association is returned. This call is especially useful when a <code>connect()</code> call has been made without first doing a <code>bind()</code> ; this call provides the only means by which you can determine the local association which has been set by the system.	
	On return, the <i>namelen</i> argument contains the actual size of the name returned in bytes.	
	If a socket was bound to <code>INADDR_ANY</code> , indicating that any of the host's IP addresses should be used for the socket, <code>getsockname()</code> will not necessarily return information about the host IP address, unless the socket has been connected with <code>connect()</code> or <code>accept()</code> .	

<b>Return Value</b>	If no error occurs, <code>getsockname()</code> returns 0. Otherwise, it returns -1, and the global variable <i>errno</i> contains one of the following values.	
<b>Error Codes</b>	EFAULT	The address of <i>name</i> or <i>namelen</i> argument is not large enough.
	EBADF	The descriptor is not a socket.
<b>See Also</b>	<code>bind()</code> , <code>socket()</code> , <code>getpeername()</code>	

### **getsockopt** Retrieve a socket option.

---

<b>Syntax</b>	<b>#include &lt;sock.h&gt;</b> <b>int getsockopt ( int s, int level, int optname, char *optval, int *optlen );</b>	
<b>Arguments</b>	<i>s</i>	A descriptor identifying a socket.
	<i>level</i>	The level at which the option is defined; the only supported <i>levels</i> are SOL_SOCKET.
	<i>optname</i>	The socket option for which the value is to be retrieved.
	<i>optval</i>	A pointer to the buffer in which the value for the requested option is to be returned.
	<i>optlen</i>	A pointer to the size of the <i>optval</i> buffer.
<b>Description</b>	<i>getsockopt()</i> retrieves the current value for a socket option associated with a socket of any type, in any state, and stores the result in <i>optval</i> . Options may exist at multiple protocol levels, but they are always present at the uppermost “socket” level. Options affect socket operations, such as whether an operation blocks or not, the routing of packets, out-of-band data transfer, etc.	
	The value associated with the selected option is returned in the buffer <i>optval</i> . The integer pointed to by <i>optlen</i> should originally contain the size of this buffer; on return, it will be set to the size of the value returned. For SO_LINGER, this will be the size of a struct <code>linger</code> ; for all other options it will be the size of an integer.	
	If the option was never set with <code>setsockopt()</code> , then <code>getsockopt()</code> returns the default value for the option.	

The following options are supported for `getsockopt()`. The Type identifies the type of data addressed by *optval*. Supported socket options are:

<b>Value</b>	<b>Type</b>	<b>Meaning</b>
SO_DONTLINGER	BOOL	If true, the SO_LINGER option is disabled.
SO_KEEPALIVE	BOOL	Keepalives are being sent.
SO_LINGER	LINGER*	Returns the current linger options.

Calling `getsockopt()` with an unsupported option will result in an error code of `ENOPROTOOPT`.

**Return Value**

If no error occurs, `getsockopt()` returns 0. Otherwise, it returns `-1`, and the global variable *errno* contains one of the following values.

**Error Codes**

EFAULT	The <code>optlen</code> argument was invalid.
ENOPROTOOPT	The option is unknown or unsupported
EBADF	The descriptor is not a socket

**See Also**

`setsockopt()`, `socket()`

**htonl** Convert an unsigned long from host to network byte order.

---

**Syntax** `#include <sock.h>`

`u_long htonl ( u_long hostlong );`

**Arguments** *hostlong* A 32-bit number in host byte order.

**Description** This routine takes a 32-bit number in host byte order and returns a 32-bit number in network byte order.

**Return Value** htonl() returns the value in network byte order.

**See Also** htons(), ntohl(), ntohs().

**htons** Convert an unsigned short from host to network byte order.

---

**Syntax** `#include <sock.h>`

`u_short htons ( u_short hostshort );`

**Arguments** *hostshort* A 16-bit number in host byte order.

**Description** This routine takes a 16-bit number in host byte order and returns a 16-bit number in network byte order.

**Return Value** htons() returns the value in network byte order.

**See Also** htonl(), ntohl(), ntohs().



**inet\_addr** Convert a string containing a dotted address into an **in\_addr**.

---

**Syntax** `#include <sock.h>`

`unsigned long inet_addr ( char *cp );`

**Arguments** *cp* A character string representing a number expressed in the Internet standard “.” notation.

**Description** This function interprets the character string specified by the *cp* parameter. This string represents a numeric Internet address expressed in the Internet standard “.” notation. The value returned is a number suitable for use as an Internet address. All Internet addresses are returned in network order (bytes ordered from left to right).

Internet Addresses

Values specified using the “.” notation take the following forms:

a.b.c.d

When four parts are specified, each is interpreted as a byte of data and assigned, from left to right, to the four bytes of an Internet address. Note that when an Internet address is viewed as a 32-bit integer quantity on the Intel architecture, the bytes referred to above appear as “d.c.b.a”. That is, the bytes on an Intel processor are ordered from right to left.

Note: The following notations are only used by Berkeley, and nowhere else on the Internet. In the interests of compatibility with their software, they are supported as specified.

**Return Value** If no error occurs, `inet_addr()` returns an unsigned long containing a suitable binary representation of the Internet address given. If the passed-in string does not contain a legitimate Internet address, for example if a portion of an “a.b.c.d” address exceeds 255, `inet_addr()` returns the value `INADDR_ANY`.

**See Also** `inet_ntoa()`

**`inet_ntoa`** **Convert a network address into a string in dotted format.**

---

**Syntax** `#include <sock.h>`

`char *inet_ntoa ( unsigned long in );`

**Arguments** *in* An Internet host address.

**Description** This function takes an Internet address specified by the *in* parameter. It returns an ASCII string representing the address in “.” notation as “a.b.c.d”. Note that the string returned by `inet_ntoa()` resides in memory which is allocated by the sockets implementation. The application should not make any assumptions about the way in which the memory is allocated. The data is guaranteed to be valid until the next sockets API call within the same thread, but no longer.

**Return Value** If no error occurs, `inet_ntoa()` returns a char pointer to a static buffer containing the text address in standard “.” notation. Otherwise, it returns `NULL`. The data should be copied before another Windows Sockets call is made.

**See Also** `inet_addr()`.

## **ioctlsocket**

## **Control the mode of a socket.**

---

### **Syntax**

```
#include <sdksoc.h>
```

### **Arguments**

```
int ioctlsocket ( int s, long cmd, u_long *argp );
```

*s* A descriptor identifying a socket.

*cmd* The command to perform on the socket *s*.

*argp* A pointer to a parameter for *cmd*.

### **Description**

This routine may be used on any socket in any state. It is used to get or retrieve operating parameters associated with the socket, independent of the protocol and communications subsystem. The following commands are supported:

Command	Semantics
FIONBIO	Enable or disable non-blocking mode on the socket <i>s</i> . <i>argp</i> points to an unsigned long, which is non-zero if non-blocking mode is to be enabled and zero if it is to be disabled. When a socket is created, it operates in blocking mode (i.e., non-blocking mode is disabled). This is consistent with BSD sockets.

### **Compatibility**

This function is a subset of ioctl() as used in Berkeley sockets.

### **Return Value**

Upon successful completion, the ioctlsocket() returns 0. Otherwise, it returns -1, and the global variable *errno* contains one of the following values.

### **Error Codes**

EINVAL *cmd* is not a valid command, or *argp* is not an acceptable parameter for *cmd*, or the command is not applicable to the type of socket supplied.

EBADF The descriptor *s* is not a socket.

### **See Also**

socket(), setsockopt(), getsockopt().

**listen** - Establish a socket to listen for incoming connection.

---

<b>Syntax</b>	<code>#include &lt;sock.h&gt;</code> <code>int listen ( int s, int backlog );</code>
<b>Arguments</b>	<i>s</i> A descriptor identifying a bound, unconnected socket. <i>backlog</i> The maximum length to which the queue of pending connections may grow.
<b>Description</b>	To accept connections, a socket is first created with <code>socket()</code> , a backlog for incoming connections is specified with <code>listen()</code> , and then the connections are accepted with <code>accept()</code> . <code>listen()</code> applies only to sockets that support connections, i.e., those of type <code>SOCK_STREAM</code> . The socket <i>s</i> is put into “passive” mode where incoming connections are acknowledged and queued pending acceptance by the process.  listen() attempts to continue to function rationally when there are no available descriptors. It will accept connections until the queue is emptied. If descriptors become available, a later call to <code>listen()</code> or <code>accept()</code> will refill the queue to the current or most recent “backlog” if possible, and then resume listening for incoming connections.
<b>Compatibility</b>	<i>backlog</i> is currently limited (silently) to 5. As in 4.3BSD, illegal values (less than 1 or greater than 5) are replaced by the nearest legal value.
<b>Return Value</b>	If no error occurs, <code>listen()</code> returns 0. Otherwise, it returns -1, and the global variable <i>errno</i> contains one of the following values.
<b>Error Codes</b>	<code>EBADF</code> The descriptor is not a socket. <code>EOPNOTSUPP</code> The referenced socket is not of a type that supports the <code>listen()</code> operation.
<b>See Also</b>	<code>accept()</code> , <code>connect()</code> , <code>socket()</code> .

**ntohl** Convert an unsigned long from network to host byte order.

---

**Syntax** `#include <sock.h>`  
`u_long ntohl ( u_long netlong );`

**Arguments** *netlong* A 32-bit number in network byte order.

**Description** This routine takes a 32-bit number in network byte order and returns a 32-bit number in host byte order.

**Return Value** `ntohl()` returns the value in host byte order.

**See Also** `htonl()`, `htons()`, `ntohs()`.

**ntohs** Convert an unsigned short from network to host byte order.

---

**Syntax** `#include <sock.h>`  
`u_short ntohs ( u_short netshort );`

**Arguments** *netshort* A 16-bit number in network byte order.

**Description** This routine takes a 16-bit number in network byte order and returns a 16-bit number in host byte order.

**Return Value** `ntohs()` returns the value in host byte order.

**See Also** `htonl()`, `htons()`, `ntohl()`.

## recv

## Receive data from a socket.

---

### Syntax

```
#include <sock.h>
```

```
int recv ( int s, char *buf, int len, int flags );
```

### Arguments

*s* A descriptor identifying a connected socket.

*buf* A buffer for the incoming data.

*len* The length of *buf*.

*flags* Specifies the way in which the call is made.

### Description

This function is used on connected datagram or stream sockets specified by the *s* parameter and is used to read incoming data.

For sockets of type SOCK\_STREAM, as much information as is currently available up to the size of the buffer supplied is returned.

For datagram sockets, data is extracted from the first enqueued datagram, up to the size of the buffer supplied. If the datagram is larger than the buffer supplied, the buffer is filled with the first part of the datagram, and the excess data is lost.

If no incoming data is available at the socket, the `recv()` call waits for data to arrive unless the socket is non-blocking. In this case a value of `-1` is returned with the error code set to `EWOULDBLOCK`. The `select()` calls may be used to determine when more data arrives.

If the socket is of type SOCK\_STREAM and the remote side has shut down the connection gracefully or the connection has been reset, a `recv()` will complete immediately with 0 bytes received.

*flags* may be used to influence the behavior of the function invocation beyond the options specified for the associated socket. That is, the semantics of this function are determined by the socket options and the *flags* parameter. The latter is constructed by “or-ing” any of the following values:

Value      Meaning

MSG\_OOB      Read out-of-band data  
(SOCK\_STREAM only)

**Return Value**

If no error occurs, `recv()` returns the number of bytes received. If the connection has been closed, it returns 0. Otherwise, it returns -1, and the global variable *errno* contains one of the following values.

**Error Codes**

EBADF	The descriptor is not a socket.
EFAULT	The buf argument pointer is invalid.
EOPNOTSUPP	MSG_OOB was specified, but the socket is not of type SOCK_STREAM.
ESHUTDOWN	The socket has been shutdown; it is not possible to <code>recv()</code> on a socket after <code>shutdown()</code> has been invoked with <i>how</i> set to 0 or 2.
EWOULDBLOCK	The socket is marked as non-blocking and the receive operation would block.
EIO	MSG_OOB was specified, but has not received out-of-band data.
ELENZERO	The length argument is zero.

**See Also**

`recvfrom()`, `read()`, `,recv()`, `send()`, `select()`, `socket()`

**recvfrom**                      **Receive a datagram and store the source address.**

---

**Syntax**                      **#include <sdksoc.h>**  
**int   recvfrom ( int s, char \*buf, int len, int flags,**  
**SOCKADDR \*from, int \*fromlen );**

**Arguments**

*s*                      A descriptor identifying a bound socket

*buf*                    A buffer for the incoming data.

*len*                    The length of *buf*.

*flags*                 Specifies the way in which the call is made.

*from*                  An optional pointer to a buffer which will hold the source address upon return.

*fromlen*              An optional pointer to the size of the *from* buffer.

**Description**              This function is used to read incoming data on a (possibly connected) socket and capture the address from which the data was sent.

For sockets of type SOCK\_STREAM, as much information as is currently available up to the size of the buffer supplied is returned. The *from* and *fromlen* parameters are ignored for SOCK\_STREAM sockets.

For datagram sockets, data is extracted from the first enqueued datagram, up to the size of the buffer supplied. If the datagram is larger than the buffer supplied, the buffer is filled with the first part of the message, and the excess data is lost.

If *from* is non-zero, and the socket is of type SOCK\_DGRAM, the network address of the peer which sent the data is copied to the corresponding SOCKADDR. The value pointed to by *fromlen* is initialized to the size of this structure, and is modified on return to indicate the actual size of the address stored there.

If no incoming data is available at the socket, the `recvfrom()` call waits for data to arrive unless the socket is non-blocking. In this case a value of -1 is returned with the error code set to EWOULDBLOCK. The `select()` calls



may be used to determine when more data arrives.

If the socket is of type `SOCK_STREAM` and the remote side has shut down the connection gracefully or the connection has been reset, a `recvfrom()` will complete immediately with 0 bytes received.

*flags* may be used to influence the behavior of the function invocation beyond the options specified for the associated socket. That is, the semantics of this function are determined by the socket options and the *flags* parameter. The latter is constructed by “or-ing” any of the following values:

<u>Value</u>	<u>Meaning</u>
<code>MSG_OOB</code> ( <code>SOCK_STREAM</code> only)	Read out-of-band data

#### **Return Value**

If no error occurs, `recvfrom()` returns the number of bytes received. If the connection has been closed, it returns 0. Otherwise, it returns -1, and the global variable *errno* contains one of the following values.

#### **Error Codes**

<code>EBADF</code>	The descriptor is not a socket.
<code>EFAULT</code>	The <i>buf</i> argument pointer is invalid.
<code>EOPNOTSUPP</code>	<code>MSG_OOB</code> was specified, but the socket is not of type <code>SOCK_STREAM</code> .
<code>ESHUTDOWN</code>	The socket has been shut down; it is not possible to <code>recvfrom()</code> on a socket after <code>shutdown()</code> has been invoked with <i>how</i> set to 0 or 2.
<code>EWOULDBLOCK</code>	The socket is marked as non-blocking and the receive operation would block.
<code>EIO</code>	<code>MSG_OOB</code> was specified, but has not received out-of-band data.
<code>ELENZERO</code>	The length argument is zero.

#### **See Also**

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`recv()`, `send()`, `socket()`.

<b>select</b>	<b>Determine the status of one or more sockets, waiting if necessary.</b>
<b>Syntax</b>	<b><code>#include &lt;sdksock.h&gt;</code> <code>int select ( int <i>nfds</i>, fd_set *<i>readfds</i>, fd_set *<i>writefds</i>, fd_set *<i>exceptfds</i>, struct timeval *<i>timeout</i> );</code></b>
<b>Arguments</b>	<p><i>nfds</i> This argument is ignored and included only for the sake of compatibility.</p> <p><i>readfds</i> An optional pointer to a set of sockets to be checked for readability.</p> <p><i>writefds</i> An optional pointer to a set of sockets to be checked for writeability.</p> <p><i>exceptfds</i> An optional pointer to a set of sockets to be checked for errors.</p> <p><i>timeout</i> The maximum time for select() to wait, or NULL for blocking operation.</p>
<b>Description</b>	<p>This function is used to determine the status of one or more sockets. For each socket, the caller may request information on read, write or error status. The set of sockets for which a given status is requested is indicated by an fd_set structure. Upon return, the structure is updated to reflect the subset of these sockets which meet the specified condition, and select() returns the number of sockets meeting the conditions. A set of macros is provided for manipulating an fd_set. These macros are compatible with those used in the Berkeley software, but the underlying representation is completely different.</p> <p>Three independent sets of descriptors are watched. Those listed in <i>readfds</i> will be watched to see if characters become available for reading, those in <i>writefds</i> will be watched to see if it is OK to immediately write on them, and those in <i>exceptfds</i> will be watched for exceptions. On exit, the sets are modified in place to indicate which descriptors actually changed status.</p> <p>Any of <i>readfds</i>, <i>writefds</i>, or <i>exceptfds</i> may be given as NULL if no descriptors are of interest.</p>

Four macros are defined in the header file `sdksoc.h` for manipulating the descriptor sets. The variable `FD_SETSIZE` determines the maximum number of descriptors in a set (the default value of `FD_SETSIZE` is 32). Internally, an `fd_set` is represented as an array of `SOCKET`'s. The macros are:

- |  |   |
|--|---|
| <code>FD_CLR(<i>s</i>, *<i>set</i>)</code>   | Removes the descriptor <i>s</i> from <i>set</i> .                   |
| <code>FD_ISSET(<i>s</i>, *<i>set</i>)</code> | Nonzero if <i>s</i> is a member of the <i>set</i> , zero otherwise. |
| <code>FD_SET(<i>s</i>, *<i>set</i>)</code>   | Adds descriptor <i>s</i> to <i>set</i> .                            |
| <code>FD_ZERO(*<i>set</i>)</code>            | Initializes the <i>set</i> to the NULL set.                         |

The parameter *timeout* controls how long the `select()` may take to complete. If *timeout* is a null pointer, `select()` will block indefinitely until at least one descriptor meets the specified criteria. Otherwise, *timeout* points to a struct `timeval` which specifies the maximum time that `select()` should wait before returning. If the `timeval` is initialized to `{0, 0}`, `select()` will return immediately; this is used to “poll” the state of the selected sockets.

**Return Value**

`select()` returns the total number of descriptors which are ready and contained in the `fd_set` structures, 0 if the time limit has expired. Otherwise, it returns `-1`, and the global variable *errno* contains one of the following values.

**Error Codes**

- |                     |  |
|---------------------|--|
| <code>EINVAL</code> | The <code>refds</code> , <code>wrfd</code> s and <code>exfd</code> s are all NULL. |
| <code>EBADF</code>  | One of the descriptor sets contains an entry which is not a socket.                |

**See Also**

`accept()`, `connect()`, `recv()`, `recvfrom()`, `send()`

## **send**                      **Send data on a connected socket.**

---

### **Syntax**

**#include <sdksock.h>**

### **Arguments**

**int send ( int s, const char \*buf, int len, int flags );**

*s*                      A descriptor identifying a connected socket.

*buf*                    A buffer containing the data to be transmitted.

*len*                    The length of the data in *buf*.

*flags*                 Specifies the way in which the call is made

### **Description**

send() is used on connected datagram or stream sockets and is used to write outgoing data on a socket. For datagram sockets, care must be taken not to exceed the maximum IP packet size of the underlying subnets.

Note that the successful completion of a send() does not indicate that the data was successfully delivered.

If no buffer space is available within the transport system to hold the data to be transmitted, send() will block unless the socket has been placed in a non-blocking I/O mode. On non-blocking SOCK\_STREAM sockets, the number of bytes written may be between 1 and the requested length, depending on buffer availability on both the local and foreign hosts. The select() call may be used to determine when it is possible to send more data.

Flags may be used to influence the behavior of the function invocation beyond the options specified for the associated socket. That is, the semantics of this function are determined by the socket options and the flags parameter. The latter is constructed by “or-ing” any of the following values:

Value	Meaning
MSG_OOB	Send out-of-band data

### **Return Value**

If no error occurs, send() returns the total number of characters sent (note that this may be less than the number indicated by *len*.). Otherwise, it returns -1, and the global variable *errno* contains one of the following values.

<b>Error Codes</b>	EFAULT	The buf argument is not in a valid part of the user address space.
	ENOTCONN	The socket is not connected.
	EBADF	The descriptor is not a socket.
	EOPNOTSUPP	MSG_OOB was specified, but the socket is not of type SOCK_STREAM.
	ESHUTDOWN	The socket has been shut down; it is not possible to send() on a socket after shutdown() has been invoked with how set to 1 or 2.
	EWOULDBLOCK	The socket is marked as non-blocking and the requested operation would block.
	EFBIG	Data written exceeds system capacity.
<b>See Also</b>	recv(), recvfrom(), socket(), sendto().	

## **sendto**

## **Send data to a specific destination.**

---

### **Syntax**

```
#include <sdksoc.h>
```

```
int sendto ( int s, char *buf, int len, int flags,  
SOCKADDR *to, int tolen );
```

### **Arguments**

*s*            A descriptor identifying a socket  
*buf*          A buffer containing the data to be transmitted.  
*len*          The length of the data in *buf*.  
*flags*        Specifies the way in which the call is made.  
*to*           An optional pointer to the address of the target  
              socket  
*tolen*        The size of the address in *to*.

### **Description**

sendto() is used on datagram or stream sockets and is used to write outgoing data on a socket.

Note that the successful completion of a sendto() does not indicate that the data was successfully delivered.

sendto() is normally used on a SOCK\_DGRAM socket to send a datagram to a specific peer socket identified by the *to* parameter. On a SOCK\_STREAM socket, the *to* and *tolen* parameters are ignored; in this case the sendto() is equivalent to send().

To send a broadcast (on a SOCK\_DGRAM only), the address in the *to* parameter should be constructed using the special IP address INADDR\_BROADCAST (defined in sdksoc.h) together with the intended port number. It is generally inadvisable for a broadcast datagram to exceed the size at which fragmentation may occur, which implies that the data portion of the datagram (excluding headers) should not exceed 512 bytes.

If no buffer space is available within the transport system to hold the data to be transmitted, sendto() will block unless the socket has been placed in a non-blocking I/O mode. On non-blocking SOCK\_STREAM sockets, the number of bytes written may be between 1 and the requested length, depending on buffer availability on both the local and foreign hosts. The select() call may be used to determine when it is possible to send more data.

*flags* may be used to influence the behavior of the function invocation beyond the options specified for the associated socket. That is, the semantics of this function is determined by the socket options and the flags parameter. The latter is constructed by “or-ing” any of the following values:

Value	Meaning
MSG_OOB	Send out-of-band data (SOCK_STREAM only)

**Return Value**

If no error occurs, `sendto()` returns the total number of characters sent (note that this may be less than the number indicated by *len*). Otherwise, it returns `-1`, and the global variable *errno* contains one of the following values.

**Error Codes**

EFAULT	The <i>buf</i> or <i>to</i> parameters are not part of the user address space, or the <i>to</i> argument is too small (less than the size of a SOCKADDR)
ENOBUFS	The system had insufficient resources to perform the operation.
ENOTCONN	The socket is not connected (SOCK_STREAM only).
EBADF	The descriptor is not a socket.
EOPNOTSUPP	MSG_OOB was specified, but the socket is not of type SOCK_STREAM.
ESHUTDOWN	The socket has been shutdown; it is not possible to <code>sendto()</code> on a socket after <code>shutdown()</code> has been invoked with <i>how</i> set to 1 or 2.
EWOULDBLOCK	The socket is marked as non-blocking and the requested operation would block.
EINVAL	The socket has not been bound with <code>bind()</code> .

**See Also**

`recv()`, `recvfrom()`, `socket()`, `send()`.

## setsockopt

## Set a socket option.

---

### syntax

```
#include <sdksoc.h>
```

```
int setsockopt
```

```
( int s, int level, int optname, char *optval, int optlen );
```

### Arguments

*s* A descriptor identifying a socket.

*level* The level at which the option is defined; the only supported level is SOL\_SOCKET.

*optname* The socket option for which the value is to be set.

*optval* A pointer to the buffer in which the value for the requested option is supplied.

*optlen* The size of the optval buffer.

### Description

setsockopt() sets the current value for a socket option associated with a socket of any type, in any state. Although options may exist at multiple protocol levels, this specification only defines options that exist at the uppermost "socket" level. Options affect socket operations, such as whether expedited data is received in the normal data stream, whether broadcast messages may be sent on the socket, etc.

There are two types of socket options: Boolean options that enable or disable a feature or behavior, and options which require an integer value or structure. To enable a Boolean option, *optval* points to a nonzero integer. To disable the option *optval* points to an integer equal to zero. *optlen* should be equal to sizeof(int) for Boolean options. For other options, *optval* points to the an integer or structure that contains the desired value for the option, and *optlen* is the length of the integer or structure.



SO\_LINGER controls the action taken when unsent data is queued on a socket and a `closesocket()` is performed. See `closesocket()` for a description of the way in which the SO\_LINGER settings affect the semantics of `closesocket()`. The application sets the desired behavior by creating a struct `linger` (pointed to by the *optval* argument) with the following elements:

```
struct linger {
    int    l_onoff;
    int    l_linger;
}
```

To enable SO\_LINGER, the application should set `l_onoff` to a non-zero value, set `l_linger` to 0 or the desired timeout (in seconds), and call `setsockopt()`. The timeout value should be in the interval between 0 to 10 (in seconds). To enable SO\_DONTLINGER (i.e., disable SO\_LINGER) `l_onoff` should be set to zero and `setsockopt()` should be called.

By default, a socket may not be bound (see `bind()`) to a local address which is already in use. On occasion, however, it may be desirable to "re-use" an address in this way. Since every connection is uniquely identified by the combination of local and remote addresses, there is no problem with having two sockets bound to the same local address as long as the remote addresses are different. To inform the Windows Sockets implementation that a `bind()` on a socket should not be disallowed because the desired address is already in use by another socket, the application should set the SO\_REUSEADDR socket option for the socket before issuing the `bind()`. Note that the option is interpreted only at the time of the `bind()`; it is therefore unnecessary (but harmless) to set the option on a socket which is not to be bound to an existing address, and setting or resetting the option after the `bind()` has no effect on this or any other socket.

An application may request that the Sockets implementation enable the use of "keep-alive" packets on TCP connections by turning on the SO\_KEEPALIVE socket option. A Sockets implementation need not support the use of keep-alives; if it does, the precise semantics are implementation-specific, but should conform to section 4.2.3.6 of RFC 1122.

The following options are supported for setsockopt(). The Type identifies the type of data addressed by *optval*.

Value	Type	Meaning
SO_DONTLINGER	BOOL	Don't block close waiting for unsent data to be sent. Setting this option is equivalent to setting SO_LINGER with l_onoff set to zero.
SO_KEEPALIVE	BOOL	Send keepalives
SO_LINGER	LINGER *	Linger on close if unsent data is present

**Return Value** If no error occurs, setsockopt() returns 0. Otherwise, it returns -1, and the global variable *errno* contains one of the following values.

Error Codes	Meaning
EFAULT	<i>optval</i> is not in a valid part of the process address space.
EINVAL	<i>level</i> is not valid, or the information in <i>optval</i> is not valid.
ENOPROTOOPT	The option is unknown or unsupported.
EBADF	The descriptor is not a socket.

**See Also** bind(), getsockopt(), ioctlsocket(), socket().

<b>shutdown</b>	<b>Disable sends and/or receives on a socket.</b>
<b>Syntax</b>	<code>#include &lt;sdksock.h&gt;</code> <code>int shutdown ( int s, int how );</code>
<b>Arguments</b>	<i>s</i> A descriptor identifying a socket. <i>how</i> A flag that describes what types of operation will no longer be allowed.
<b>Description</b>	<p>shutdown() is used on all types of sockets to disable reception, transmission, or both.</p> <p>If <i>how</i> is 0, subsequent receives on the socket will be disallowed. This has no effect on the lower protocol layers. For TCP, the TCP window is not changed and incoming data will be accepted (but not acknowledged) until the window is exhausted. For UDP, incoming datagrams are accepted and queued.</p> <p>If <i>how</i> is 1, subsequent sends are disallowed. For TCP sockets, a FIN will be sent.</p> <p>Setting <i>how</i> to 2 disables both sends and receives as described above.</p> <p>Note that shutdown() does not close the socket, and resources attached to the socket will not be freed until closesocket() is invoked.</p>
<b>Comments</b>	<p>shutdown() does not block regardless of the SO_LINGER setting on the socket.</p> <p>An application should not rely on being able to re-use a socket after it has been shut down. In particular, a Sockets implementation is not required to support the use of connect() on such a socket.</p>
<b>Return Value</b>	If no error occurs, shutdown() returns 0. Otherwise, it returns -1, and the global variable <i>errno</i> contains one of the following values.
<b>Error Codes</b>	<p>EINVAL <i>how</i> is not valid</p> <p>ENOTCONN The socket is not connected (SOCK_STREAM only).</p> <p>EBADF The descriptor is not a socket</p>
<b>See Also</b>	connect(), socket().

## socket

## Create a socket.

---

### Syntax

```
#include <sock.h>
```

```
int socket ( int af, int type, int protocol );
```

### Arguments

*af* An address format specification. The only format currently supported is AF\_INET, which is the ARPA Internet address format.

*type* A type specification for the new socket.

*protocol* A particular protocol to be used with the socket, or 0 if the caller does not wish to specify a protocol.

### Description

socket() allocates a socket descriptor of the specified address family, data type and protocol, as well as related resources. If a protocol is not specified (i.e., equal to 0), the default for the specified connection mode is used.

Only a single protocol exists to support a particular socket type using a given address format. The protocol number to use is particular to the "communication domain" in which communication is to take place.

The following type specifications are supported:

#### Type Explanation

##### SOCK\_STREAM

Provides sequenced, reliable, two-way, connection-based byte streams with an out-of-band data transmission mechanism. Uses TCP for the Internet address family.

##### SOCK\_DGRAM

Supports datagrams, which are connectionless, unreliable buffers of a fixed (typically small) maximum length. Uses UDP for the Internet address family.

Sockets of type `SOCK_STREAM` are full-duplex byte streams. A stream socket must be in a connected state before any data may be sent or received on it. A connection to another socket is created with a `connect()` call. Once connected, data may be transferred using `send()` and `recv()` calls. When a session has been completed, a `closesocket()` must be performed. Out-of-band data may also be transmitted as described in `send()` and received as described in `recv()`.

The communications protocols used to implement a `SOCK_STREAM` to ensure that data is not lost or duplicated.

`SOCK_DGRAM` sockets allow sending and receiving of datagrams to and from arbitrary peers using `sendto()` and `recvfrom()`. If such a socket is `connect()`'ed to a specific peer, datagrams may be sent to that peer using `send()` and may be received from (only) this peer using `recv()`.

**Return Value**

If no error occurs, `socket()` returns a descriptor referencing the new socket. Otherwise, it returns -1, and the global variable `errno` contains one of the following values.

**Error Codes**

<code>EMFILE</code>	No more file descriptors are available.
<code>EPROTONOSUPP</code> <code>RT</code>	The specified address family or protocol is not supported.

**See Also**

`accept()`, `bind()`, `connect()`, `getsockname()`, `getsockopt()`, `setsockopt()`, `listen()`, `recv()`, `recvfrom()`, `select()`, `send()`, `sendto()`, `shutdown()`, `ioctlsocket()`.

## 3-3 Simplified Socket Library Reference

**net\_get\_gateway**    Get local default gateway.

---

**Syntax**            `#include <sdknet.h>`  
`u_long    net_get_gateway ( void );`

**Arguments**        N/A

**Description**      Get local default gateway.

**Return Value**     default gateway IP address.

**net\_get\_IP**        Get local IP address.

---

**Syntax**            `#include <sdknet.h>`  
`u_long    net_get_IP ( void );`

**Arguments**        N/A

**Description**      Get local IP address.

**Return Value**     local IP address

**net\_get\_MAC\_address**    Get MAC address.

---

**Syntax**            `#include <sdknet.h>`  
`void    net_get_MAC_address ( u_char *mac );`

**Arguments**        *mac*            Get MAC address data buffer pointer.

**Description**      Get MAC address.

**Return Value**     System copies the host MAC address to the *mac* input buffer.

**net\_get\_netmask**    Get local subnet mask.

---

**Syntax**            `#include <sdknet.h>`  
`u_long    net_get_netmask ( void );`

**Arguments**        N/A

**Description**      Get local subnet mask.

**Return Value**     local netmask.

## **tcp\_close**                      **Close a local TCP port.**

---

**Syntax**                      **#include <sdknet.h>**  
**int tcp\_close ( int *handle* );**

**Arguments**                      *handle*    the value returned from tcp\_open().

**Description**                      Close a local TCP port.

**Return Value**                      0      O.K  
   -1     error handle number.

**See Also**

## **tcp\_connect**                      **Connect to specific host IP and port.**

---

**Syntax**                      **#include <sdknet.h>**  
**int tcp\_connect**  
**( int *handle*, u\_long *rip*, int *rport*, long *tout* );**

**Arguments**                      *handle*    the value return from tcp\_open().  
*rip*        remote host IP address that user wants to link.  
*rport*      remote host TCP port no.  
*tout*        wait for TCP connection time out value: ms.  
   0 will wait for OK or fail.

**Description**                      Connect to specific host IP and port.

**Return Value**                      1    connect OK  
   0    connect fail.  
   -1   error handle number.  
   -2   error argument.  
   -3   timeout counter reached.  
   -4   error state; already connected.  
   -5   the *rip:rport* already in use.





**tcp\_iqueue**            **Get the size of data accumulated in TCP driver's input buffer.**

---

**Syntax**                **#include <sdknet.h>**  
**int tcp\_iqueue ( int handle )**

**Arguments**            *handle*    the value returned from tcp\_open()

**Description**            Get the size of data accumulated in TCP driver's input buffer.

**Return Value**            >=0      TCP input buffer queued data size.  
                             -1        error handle number.  
                             -2        This is not a TCP handle.  
                             -3        TCP not connected.

**tcp\_listen**             **Places a socket in a state where it is listening for an incoming connection.**

---

**Syntax**                **#include <sdknet.h>**  
**int tcp\_listen ( int handle, long tout );**

**Arguments**            *handle*    the value return from tcp\_open().  
*tout*        wait for listen time out value, unit is ms.  
                             0 for wait for someone to connect.

**Description**            Places a socket a state where it is listening for an incoming connection.

**Return Value**            1    connect OK or already connected.  
                             0    connect fail.  
                             -1   error handle number.  
                             -2   this handle was opened by tcp\_open().  
                             -3   timeout counter reached.  
                             -4   error state; already connected.

**tcp\_listen\_nowait** Places a socket in a state where it is listening for an incoming connection no wait.

---

**Syntax** `#include <sdknet.h>`  
`int tcp_listen_nowait ( int handle );`

**Arguments** *handle* the value returned from tcp\_open()

**Description** Places a socket a state where it is listening for an incoming connection no wait.

**Return Value** 0 start to listen.  
-1 error handle number  
-2 this handle was opened by tcp\_open().  
-3 error state; already connected.

**tcp\_listento** Listen for a specific incoming connection.

---

**Syntax** `#include <sdknet.h>`  
`int tcp_listento ( int handle, u_long rip, int rport, long tout );`

**Arguments** *handle* the value returned from tcp\_open()  
*rip* remote host IP address that user wants to link to.  
0 indicates don't case remote IP address.  
*rport* remote host TCP port No. 0 indicates don't case the TCP port number.  
*tout* wait for listen timeout value; unit is ms.

**Description** Listen for a specific incoming connection.

**Return Value** 1 connect OK or already connected.  
0 connect fail.  
-1 error handle number.  
-2 this handle was opened by tcp\_open().  
-3 timeout counter reached.  
-4 error state; already connected.

---

**tcp\_listeno\_nowait Listen for a specific incoming connection no wait.**

---

<b>Syntax</b>	<b>#include &lt;sdknet.h&gt;</b> <b>int tcp_listeno_nowait</b> <b>( int handle, u_long rip, int rport );</b>
<b>Arguments</b>	<i>handle</i> the value returned from tcp_open() <i>rip</i> remote host IP address that user wants to link to. 0 indicates don't case remote IP address. <i>rport</i> remote host's TCP port No. 0 indicates don't case the TCP port number.
<b>Description</b>	Listen for a specific incoming connection no wait.
<b>Return Value</b>	0 start to listen. -1 error handle number -2 this handle was opened by tcp_open(). -3 error state; already connected.

---

**tcp\_ofree Size of free space in TCP driver's input buffer.**

---

<b>Syntax</b>	<b>#include &lt;sdknet.h&gt;</b> <b>int tcp_ofree ( int handle )</b>
<b>Arguments</b>	<i>handle</i> the value returned from tcp_open()
<b>Description</b>	Size of free space in TCP driver's input buffer.
<b>Return Value</b>	>=0 TCP output buffer's free size. -1 error handle number. -2 This is not a TCP handle. -3 TCP not connected.

---

**tcp\_open Open a local TCP port.**

---

<b>Syntax</b>	<b>#include &lt;sdknet.h&gt;</b> <b>int tcp_open ( int port );</b>
<b>Arguments</b>	<i>port</i> local TCP port number.
<b>Description</b>	Open a local TCP port.
<b>Return Value</b>	>=0 open handle -1 open fail.

**tcp\_recv**                      **Receives data from a connected socket.**

---

**Syntax**                      **#include <sdknet.h>**  
**int tcp\_recv ( int *handle*, char \**buffer*, int *len* );**

**Arguments**                      *handle*        the value returned from tcp\_open()  
                                      *buffer*        the received data buffer pointer.  
                                      *len*            buffer length

**Description**                      Receives data from a connected socket.

**Return Value**                      >=0        received data length.  
                                      -1            error handle number.  
                                      -2            error argument.  
                                      -3            TCP not connected.

**tcp\_send**                      **Sends data on a connected socket.**

---

**Syntax**                      **#include <sdknet.h>**  
**int tcp\_send ( int *handle*, char \**buffer*, int *len* );**

**Arguments**                      *handle*        the value return from tcp\_open()  
                                      *buffer*        the send out data buffer pointer.  
                                      *len*            data length

**Description**                      Sends data on a connected socket.

**Return Value**                      >=0        send out data length.  
                                      -1            error handle number.  
                                      -2            error argument.  
                                      -3            TCP not connected.

## tcp\_state

Get TCP state.

---

### Syntax

```
#include <sdknet.h>
```

```
int tcp_state ( int handle )
```

### Arguments

*handle* the value returned from tcp\_open()

### Description

Get TCP state.

### Return Value

0 TCP closed.  
1 TCP listen.  
2 TCP connecting.  
3 TCP connected.  
4 TCP close wait (remote closed).  
5 TCP closing  
-1 error handle.  
-2 This handle is not a TCP handle.

## udp\_close

Close a local UDP port.

---

### Syntax

```
#include <sdknet.h>
```

```
int udp_close ( int handle );
```

### Arguments

*handle* The value return from udp\_open().

### Description

Close a local UDP port.

### Return Value

0 close OK  
-1 error handle number.

## udp\_iqueue

Get the size of data accumulated in UDP driver's input buffer.

---

### Syntax

```
#include <sdknet.h>
```

```
int udp_iqueue ( int handle )
```

### Arguments

*handle* the value returned from udp\_open()

### Description

Get the size of data accumulated in UDP driver's input buffer.

### Return Value

>=0 UDP input buffer queued data size.  
-1 error handle number.  
-2 this is not a UDP handle.

---

**udp\_ofree**                    **Size of free space in UDP driver's input buffer.**

---

**Syntax**                    `#include <sdknet.h>`  
`int udp_ofree ( int handle )`

**Arguments**                *handle*     the value returned from udp\_open()

**Description**             Size of free space in UDP driver's input buffer.

**Return Value**            `>=0`     UDP output buffer free size.  
                             `-1`        error handle number.  
                             `-2`        this is not a UDP handle.

---

**udp\_open**                    **Open a local UDP port.**

---

**Syntax**                    `#include <sdknet.h>`  
`int udp_open ( int port )`

**Arguments**                *port*     the local UDP port number

**Description**             Open a local UDP port.

**Return Value**            `>=0`     open handle.  
                             `-1`        open fail.

---

**udp\_rcv**                    **Receives data from a specific source address.**

---

**Syntax**                    `#include <sdknet.h>`  
`int udp_rcv`  
`( int handle, u_long *rip, int *rport, char *buf, int len );`

**Arguments**                *handle*     the value return from udp\_open().  
*rip*         rcv from host IP address pointer.  
*rport*       rcv from host UDP port number pointer.  
*buf*         rcv data buffer pointer.  
*len*         rcv data buffer length.

**Description**             Receives data from a specific source address.

**Return Value**            `>= 0` rcv data length.  
                             `-1`    rcv failed.

## **udp\_send**

**Sends data to a specific destination.**

---

### **Syntax**

```
#include <sdknet.h>  
int udp_send ( int handle, u_long rip, int rport, char  
*buf, int len );
```

### **Arguments**

*handle*     the value returned from udp\_open().  
*rip*        send to host IP address.  
*rport*      send to host UDP port number.  
*buf*        send data buffer pointer.  
*len*        send data length

### **Description**

Sends data to a specific destination.

### **Return Value**

$\geq 0$      sent out data length.  
-1        send failed.

## 3-4 System Control Library Reference

**[sys\\_clock\\_ms](#)**      **Read the server's time (milliseconds) count from power-up.**

---

**Syntax**            **#include <sdksys.h>**  
**unsigned long    sys\_clock\_ms ( void );**

**Arguments**        N/A

**Description**      Read the server's time (milliseconds) count from power-up.

**Return Value**     This function returns server's time counter in milliseconds.

**See Also**          sys\_clock\_s()

**[sys\\_clock\\_s](#)**        **Read the server's time (seconds) count from power-up.**

---

**Syntax**            **#include <sdksys.h>**  
**unsigned long    sys\_clock\_s ( void );**

**Arguments**        N/A

**Description**      Read the server's time (seconds) count from power-up.

**Return Value**     This function returns server's time counter in seconds.

**See Also**          sys\_clock\_ms()

**[sys\\_disable\\_watchdog](#)**      **Disable watchdog.**

---

**Syntax**            **#include <sdksys.h>**  
**void    sys\_watchdog\_disable( void );**

**Arguments**        N/A

**Description**      Disable watchdog.

**Return Value**     N/A



<u>sys_enable_watchdog</u>	<b>Enable watchdog.</b>	
<b>Syntax</b>	<b>int sys_enable_watchdog ( int <i>mode</i> );</b>	
<b>Arguments</b>	<i>mode</i>	1 watch-dog reset timeout value is 335ms. 2 watch-dog reset timeout value is 419ms. 3 watch-dog reset timeout value is 671ms. 4 watch-dog reset timeout value is 838ms. 5 watch-dog reset timeout value is 1.34s. 6 watch-dog reset timeout value is 1.68s. 7 watch-dog reset timeout value is 2.68s. 8 watch-dog reset timeout value is 3.35s.
<b>Description</b>	Enable watchdog.	
<b>Return Value</b>	0	OK
	-1	error argument.

<u>sys_exit</u>	<b>Exit application.</b>	
<b>Syntax</b>	<b>#include &lt;sdksys.h&gt;</b>	
	<b>Void sys_exit ( void );</b>	
<b>Arguments</b>	N/A	
<b>Description</b>	To exit user application and return to kernel. It will let the user application stop it.	
<b>Return Value</b>	N/A	
<b>See Also</b>	N/A	

## sys\_get\_info

## Get server general information.

---

### Syntax

```
#include <sdksys.h>
```

### Arguments

```
int sys_get_info ( struct sdk_sysinfo *info );  
info A pointer to a buffer that will receive the server  
general information.
```

### Description

```
struct sdk_version {  
    unsigned short    ext_version;  
    unsigned char     sub_version;  
    unsigned char     main_version;  
};  
e.g., Ver 1.20.3, the main version is 1, sub_version is 20  
and ext_version is 3.  
struct sdk_sysinfo {  
    struct sdk_version    firmware_version; /* Server's  
                                           firmware  
                                           version. */  
    unsigned long        serial_no; /* Server's serial  
                                     number */  
    unsigned short       product_id; /* Server's  
                                     product ID */  
    unsigned char        MAC_addr[6]; /* Server  
                                     Ethernet MAC  
                                     address */  
    struct sdk_version    ap_version; /* User's AP  
                                     version */  
    unsigned short       ap_date_year; /* Date of AP:  
                                     A.D. e.g. 2002 */  
    unsigned char        ap_date_month; /* Range: 1 - 12  
                                     */  
    unsigned char        ap_date_day; /* Range: 1 - 31  
                                     */  
    unsigned char        ap_time_hour; /* Range: 0 - 23  
                                     */  
    unsigned char        ap_time_minute; /* Range: 0 - 59  
                                     */  
};
```

**Return Value** `sys_get_info()` returns the buffer data length of the information structure. Return of 0 indicates the argument is invalid.

---

**`sys_get_SerialType` Get async port interface signal type.**

---

**Syntax** `#include <sdksys.h>`  
`sys_get_SerialType ( int port );`

**Arguments** *port* Async serial port number

**Description** Get async port interface signal type.

**Return Value**

0	RS-232
1	RS-422
2	RS-485 (2w)
3	RS-485 (4w)

---

-1 Bad port

---

**`sys_get_WatchdogStatus` Get watchdog status.**

---

**Syntax** `#include <sdksys.h>`  
`int sys_get_WatchdogStatus ( void );`

**Arguments** N/A

**Description** Get watchdog status.

**Return Value**

0	watch-dog timer is disabled.
1	watch-dog reset timeout value is 335ms. (refer to <code>sys_watchdog_enable()</code> )
8	watch-dog reset timeout value is 3.35s.

---

**`sys_restart_system` Restart system.**

---

**Syntax** `#include <sdksys.h>`  
`Void sys_restart_system ( void );`

**Arguments** N/A

**Description** Restart system.

**Return Value** N/A

## **sys\_restart\_UserAP** Restart user AP.

---

<b>Syntax</b>	<code>#include &lt;sdksys.h&gt;</code> <code>void sys_restart_UserAP ( void );</code>
<b>Arguments</b>	N/A
<b>Description</b>	Restart user AP.
<b>Return Value</b>	N/A

## **sys\_Set\_RegisterID** Set Application ID.

---

<b>Syntax</b>	<code>#include &lt;sdksys.h&gt;</code> <code>void sys_Set_RegisterID ( u_long id );</code>
<b>Arguments</b>	<i>id</i> Application ID.
<b>Description</b>	It let user the application ID. User can get by DSCI. And 0x80000000 to 0xFFFFFFFF is reversed for MOXA only. User just can use 0x00000000 to 0x7FFFFFFF. Your application starts to run to need first to call it.
<b>Return Value</b>	N/A
<b>See Also</b>	N/A

## **sys\_set\_SerialType** Set async port interface signal type.

---

<b>Syntax</b>	<code>#include &lt;sdksys.h&gt;</code> <code>sys_set_SerialType ( int port, int type );</code>
<b>Arguments</b>	<i>port</i> Async serial port number 0 RS-232 1 RS-422 2 RS-485 (2w) 3 RS-485 (4w) <i>Note: Not supported by NPort 4511.</i>
<b>Description</b>	Set async port interface signal type.
<b>Return Value</b>	0 Set OK -1 Bad port -2 Bad parameter (Cannot set this interface type)

**[sys\\_sleep\\_ms](#)**                    **Task sleep time (milliseconds).**

---

**Syntax**                            **#include <sdksys.h>**  
**int sys\_sleep\_ms ( long *time\_ms* );**  
*time\_ms*                    Task sleep time in milliseconds.

**Arguments**                        *time\_ms*                    Task sleep time in milliseconds.

**Description**                      Task sleep time (milliseconds).

**Return Value**                      This function always returns 0.

**See Also**                            sys\_clock\_s(), sys\_clock\_ms()

**[sys\\_timeout](#)**                    **Set the timeout event service routine.**

---

**Syntax**                            **#include <sdksys.h>**  
**int sys\_timeout ( void (\**func*)(), long *time\_ms* );**  
*func*                        The timeout event service routine.  
*time\_ms*                      Timeout value in milliseconds.

**Arguments**                        *func*                        The timeout event service routine.  
*time\_ms*                      Timeout value in milliseconds.

**Description**                      Set the timeout event service routine.

**Return Value**                      0                            No errors.  
EINVAL                        The isr argument event function pointer is invalid.  
ENOBUFS                        No resources.

**See Also**                            sys\_clock\_s(), sys\_clock\_ms(), sys\_sleep\_ms()..

## **sys\_event\_suspend**      Suspend interrupt

---

<b>Syntax</b>	<b>#include &lt;sdksys.h&gt;</b> <b>void sys_event_suspend(int type, u_long args);</b>
<b>Arguments</b>	<i>type</i> interrupt type 0 → sys_timeout 1 → sio_term_irq 2 → sio_cnt_irq 3 → sio_modem_irq 4 → sio_break_irq 5 → sio_tx_Empty_irq  <i>args</i> If “type” is 0, “args” is the timeouts interrupt subroutine. If “type” is not 0, “args” is the serial port number. Eq. 1 for NPort 4511’s serial port.
<b>Description</b>	<p>This function suspends the specific interrupt when the subroutine is called not, from specific interrupt, preventing unpredictable situations from occurring. This function is usually called at the beginning of a subroutine.</p> <p>For example, suppose brk_isr() is sio_break_irq() interrupt subroutine (ISR). If it is called from the main program instead of a break interrupt, this function will prevent unpredictable results.</p>
<b>Return Value</b>	0            OK -1          Fail
<b>See Also</b>	sys_event_resume

<code>sys_event_resume</code>	Resume interrupt
<b>Syntax</b>	<code>#include &lt;sdksys.h&gt;</code> <code>void sys_event_resume(int type, u_long args);</code>
<b>Arguments</b>	<p><i>type</i> interrupt type</p> <ul style="list-style-type: none"> <li>0 → <code>sys_timeout</code></li> <li>1 → <code>sio_term_irq</code></li> <li>2 → <code>sio_cnt_irq</code></li> <li>3 → <code>sio_modem_irq</code></li> <li>4 → <code>sio_break_irq</code></li> <li>5 → <code>sio_tx_Empty_irq</code></li> </ul> <p><i>args</i> If “type” is 0, “args” is the timeouts interrupt subroutine. If “type” is not 0, “args” is the serial port number. Eq. 1 for NPort 4511’s serial port.</p>
<b>Description</b>	<p>This will resume the interrupt that is suspended by <code>sys_event_suspend</code> in subroutine.</p> <p>This function is usually called at the end of the subroutine.</p>
<b>Return Value</b>	<p>0 OK</p> <p>-1 Fail</p>
<b>See Also</b>	<code>sys_event_suspend</code>

## 3-5 Flash ROM Access Library Reference

<b>flash_erase</b>	<b>Erase flash-ROM.</b>
<b>Syntax</b>	<b>#include &lt;sdkflash.h&gt;</b> <b>int flash_erase ( void )</b>
<b>Arguments</b>	N/A
<b>Description</b>	Erase flash-ROM.
<b>Return Value</b>	0 OK -1 fail.
<b>flash_length</b>	<b>Get current data length at the flash-ROM.</b>
<b>Syntax</b>	<b>#include &lt;sdkflash.h&gt;</b> <b>long flash_length ( void )</b>
<b>Arguments</b>	N/A
<b>Description</b>	Get current data length at the flash-ROM
<b>Return Value</b>	>=0 Current data length at the flash-ROM. 0 after calling sys_flash_erase(). Max. length is 65536. (64 KB).
<b>flash_read</b>	<b>Read data from the flash-ROM.</b>
<b>Syntax</b>	<b>#include &lt;sdkflash.h&gt;</b> <b>Long flash_read</b> <b>( long offset, char *buffer, long size );</b>
<b>Arguments</b>	<i>buffer</i> : read buffer pointer. <i>size</i> buffer size.
<b>Description</b>	Read data from the flash-ROM.
<b>Return Value</b>	>=0 read data size. -1 read failed.
<b>flash_write</b>	<b>Write data to the flash-ROM.</b>
<b>Syntax</b>	<b>#include &lt;sdkflash.h&gt;</b> <b>long flash_write ( char *buffer, long size );</b>
<b>Arguments</b>	<i>buffer</i> write data buffer pointer. <i>size</i> : write data size → from 1 to 65536
<b>Description</b>	Write data to the flash-ROM.
<b>Return Value</b>	>0 write length. -1 write failed -2 Need to erase the flash-ROM first.



## 3-6 Debug Library Reference

<b>dbg_put_block</b>	<b>Print out a block of data for debugging</b>
<b>Syntax</b>	<pre>#include &lt;sdkdbg.h&gt; int  dbg_put_block ( char *buf, int len );</pre>
<b>Arguments</b>	<i>buf</i> The print out debugging data buffer pointer. <i>len</i> length of the debugging data buffer.
<b>Description</b>	Print out a block of data for debugging.
<b>Return Value</b>	This function returns the length of print out messages.
<b>See Also</b>	dbg_put_ch(), dbg_put_word(), dbg_put_doubleword(), dbg_put_word_hex(), dbg_put_doubleword_hex(), dbg_put_IP(), dbg_put_string.
<b>dbg_put_doubleword</b>	<b>Print out a 4-byte unsigned long value for debugging.</b>
<b>Syntax</b>	<pre>#include &lt;sdkdbg.h&gt; int  dbg_put_doubleword ( unsigned long value );</pre>
<b>Arguments</b>	<i>value</i> The printed out unsigned long value.
<b>Description</b>	Print out a 4-byte unsigned long value for debugging.
<b>Return Value</b>	This function returns the length of print out messages
<b>See Also</b>	dbg_put_ch(), dbg_put_block(), dbg_put_word(), dbg_put_word_hex(), dbg_put_doubleword_hex(), dbg_put_IP(), dbg_put_string().
<b>dbg_put_doubleword_hex</b>	<b>Print out a 4-byte unsigned long value with HEX format for debugging.</b>
<b>Syntax</b>	<pre>#include &lt;sdkdbg.h&gt; int  dbg_put_doubleword_hex ( unsigned long value );</pre>
<b>Arguments</b>	<i>value</i> The printed out unsigned long value.
<b>Description</b>	Print out a 4-byte unsigned long value with HEX format for debugging.
<b>Return Value</b>	This function returns the length of print out messages.
<b>See Also</b>	dbg_put_ch(), dbg_put_block(), dbg_put_word(), dbg_put_doubleword(), dbg_put_word_hex(), dbg_put_IP(), dbg_put_string().

## **dbg\_put\_ch**

**Print out a character for debugging.**

---

**Syntax**

```
#include <sdkdbg.h>
```

**Arguments**

```
int dbg_put_ch ( char ch );
```

*ch* The character value that will be printed out

**Description**

Print out a character for debugging.

**Return Value**

This function returns the length of the printed out messages.

**See Also**

dbg\_put\_block(), dbg\_put\_word(),  
dbg\_put\_doubleword(), dbg\_put\_word\_hex(),  
dbg\_put\_doubleword\_hex(), dbg\_put\_IP(),  
dbg\_put\_string().

## **dbg\_put\_IP**

**Print out an IP address in the a.b.c.d format for debugging.**

---

**Syntax**

```
#include <sdkdbg.h>
```

**Arguments**

```
int dbg_put_IP ( unsigned long ipaddr );
```

*ipaddr* The printed out Internet host's IP address.

**Description**

Print out an IP address in the a.b.c.d format for debugging.

**Return Value**

This function returns the length of print out messages.

**See Also**

dbg\_put\_ch(), dbg\_put\_block(), dbg\_put\_word(),  
dbg\_put\_doubleword(), dbg\_put\_word\_hex(),  
dbg\_put\_doubleword\_hex(), dbg\_put\_string().

## **dbg\_put\_string**

**Print out a string for debugging.**

---

**Syntax**

```
#include <sdkdbg.h>
```

**Arguments**

```
int dbg_put_string ( char *buf );
```

*buf* The printed out debugging data buffer's pointer.

**Description**

Print out a string for debugging.

**Return Value**

This function returns the length of print out messages.

**See Also**

dbg\_put\_ch(), dbg\_put\_block(), dbg\_put\_word(),  
dbg\_put\_doubleword(), dbg\_put\_word\_hex(),  
dbg\_put\_doubleword\_hex(), dbg\_put\_IP().

## dbg\_put\_word

Print out a 2-byte unsigned integer value for debugging.

---

### Syntax

```
#include <sdkdbg.h>
```

### Arguments

```
int dbg_put_word ( unsigned short value );
```

*value* The printed out unsigned short value.

### Description

Print out a 2-byte unsigned integer value for debugging.

### Return Value

This function returns the length of print out messages.

### See Also

dbg\_put\_ch(), dbg\_put\_block(), dbg\_put\_doubleword(),  
dbg\_put\_word\_hex(), dbg\_put\_doubleword\_hex(),  
dbg\_put\_IP(), dbg\_put\_string().

## dbg\_put\_word\_hex

Print out a 2-byte unsigned integer value with HEX format for debugging.

---

### Syntax

```
#include <sdkdbg.h>
```

### Arguments

```
int dbg_put_word_hex ( unsigned short value );
```

*value* The print out unsigned short value.

### Description

Print out a 2-byte unsigned integer value with HEX format for debugging.

### Return Value

This function returns the length of print out messages.

### See Also

dbg\_put\_ch(), dbg\_put\_block(), dbg\_put\_word(),  
dbg\_put\_doubleword(), dbg\_put\_doubleword\_hex(),  
dbg\_put\_IP(), dbg\_put\_string().

## External Function Calls for SDK

---

We have tested the following standard Turbo C string functions with SDK, and have verified that they can be used without any problem.

Function Name	Description
strcat()	Append a string.
strchr()	Find a character in a string.
strcmp()	Compare strings.
strcpy()	Copy a string.
strlwr()	Convert a string to lowercase.
strupr()	Convert a string to uppercase.
strlen()	Get the length of a string.
atoi()	Convert strings to integer.
atol()	Convert strings to long.
itoa()	Convert an integer to a string.
ltoa()	Convert a long integer to a string.

Note that to use these string functions, you must link to the **cs.lib** library file, with a `tlink` command similar to the one shown here.

```
%path:>tlink /t /s c0sdk+ap, ap, ap,  
moxa_sdk+c:\tc\lib\cs.lib
```

---

**NOTE**     *It is important to keep in mind that you must use the **complete path** to link to the `cs.lib` library file.*

---

If you would like to use other Turbo C standard functions, we cannot guarantee that they will work with SDK. (When using Borland C, use the same method as for Turbo C.)

---

**NOTE**     *There are several types of function calls that **must not** be used in programs for NPort-4511. They are:*

*System I/O: such as printf()*

*System Interrupt: open()*

*System Memory Allocate: malloc()*

---