

## **Protective Circuits**

Short Circuit Protection
Inrush Current Protection
Drive Overtemperature Protection
Undervoltage Protection
Regeneration Protection

## Environmental Specifications

Operating Temperature Still Air: 45°C (113°F)

Moving Air: 50°C (122°F) Minimum: 0°C (32°F)

Storage Temperature:  $-40^{\circ}C - 85^{\circ}C \ (-40^{\circ}F - 185^{\circ}F)$ 

Humidity:

0 - 95%, non-condensing



# Troubleshooting

Commonly used status commands (binary status bits are numbered 1 to n, from left to right):

TERRLG Error log reports the last 10 error conditions

(cleared with CERRLG).

TAS General report, including fault conditions.

TASX Additional report of conditions not covered with

TAS

TIN

TCS If TASX bit #7 or bit #28 is set, you can identify

the cause with TCS.

TINO Bit #6 indicates status of Enable input ("1" = OK to enable drive).

Status of digital inputs, including end-of-travel

TOUT Status of digital outputs.

You must configure all motor parameters. Be sure to follow the drive configuration procedure (see *Chapter 2 Installation*).

Any fault condition causes the drive to shut down.

The drive can not be enabled (DRIVE1) unless the Enable input is grounded and the Reset input is not grounded.

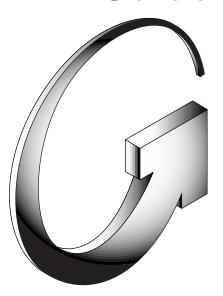
Use one of three methods to reset the drive (all command settings are remembered after reset):

Issue the RESET command.

Momentarily close the Reset input.

Cycle power to the drive.

# Quick Reference Guide



# Gemini GT6 Series Digital Stepper Controller/Drive

Compumotor Division
Parker Hannifin Corporation
p/n 88-018375-01 A (effective December 17, 1999)



To configure all drive parameters, connect a PC or HPC to this port. Use Motion Planner or Pocket Motion Planner for drive configuration.

