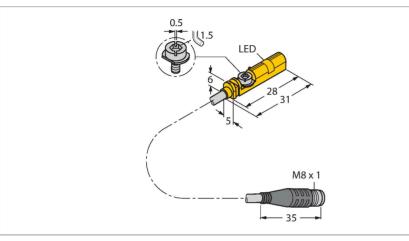


BIM-UNT-AP7X-0.3-PSG3S Magnetic Field Sensor - For Pneumatic Cylinders



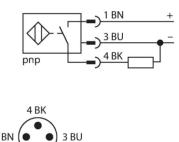
Technical data

Туре	BIM-UNT-AP7X-0.3-PSG3S
ID no.	4685742
Pass speed	≤ 10 m/s
Repeatability	≤ ± 0.1 mm
Temperature drift	≤ 0.1 mm
Hysteresis	≤ 1 mm
Ambient temperature	-25+70 °C
Operating voltage	1030 VDC
Residual ripple	≤ 10 % U _{ss}
DC rated operational current	≤ 100 mA
No-load current	≤ 10 mA
Residual current	≤ 0.1 mA
Isolation test voltage	≤ 0.5 kV
Short-circuit protection	no
Voltage drop at I _e	≤ 1.4 V
Wire breakage/Reverse polarity protection	yes / yes (voltage supply)
Output function	3-wire, NO contact, PNP
Switching frequency	1 kHz
Design	Rectangular, UNT
Dimensions	28 x 5 x 6 mm
Housing material	Plastic, PP
Active area material	Plastic, PP
Tightening torque fixing screw	0.4 Nm
Electrical connection	Cable with connector, Ø 8 mm

Features

- For T-groove cylinders without mounting accessories
- Optional accessories for mounting on other cylindrical housings.
- One-hand mounting possible
- Fine adjustment tool and stopper directly mountable on the sensor
- Stable mounting
- Magneto-resistive sensor
- DC 3-wire, 10...30 VDC
- NO contact, PNP output
- Pigtail with male end, Ø 8 mm

Wiring diagram



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Functional principle Magnetic field sensors are activated by magnetic fields and are used, in particular, for the detection of the piston position in pneumatic cylinders. As magnetic fields can permeate non-magnetizable metals, they detect a permanent magnet attached to the piston through the aluminium cylinder wall.

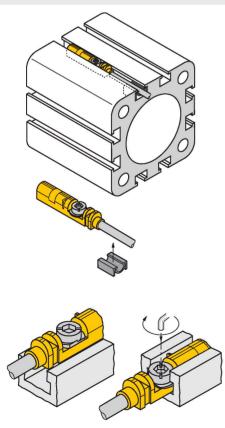


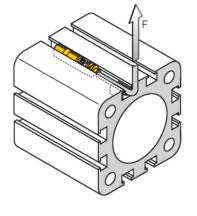
Technical data

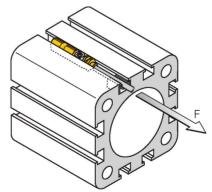
Cable quality	Ø 3 mm, Gray, Lif9Y-11Y, PUR, 0.3 m
	Suited for E-ChainSystems® acc. to manufacturers declaration H1063M
Core cross-section	3 x 0.14 mm ²
Vibration resistance	55 Hz (1 mm)
Shock resistance	30 g (11 ms)
Protection class	IP68
MTTF	2283 years acc. to SN 29500 (Ed. 99) 40 °C
Mounting on the following profiles	
Cylindrical design	
Switching state	LED, Yellow
Included in delivery	cable clip

Mounting instructions

Mounting instructions/Description





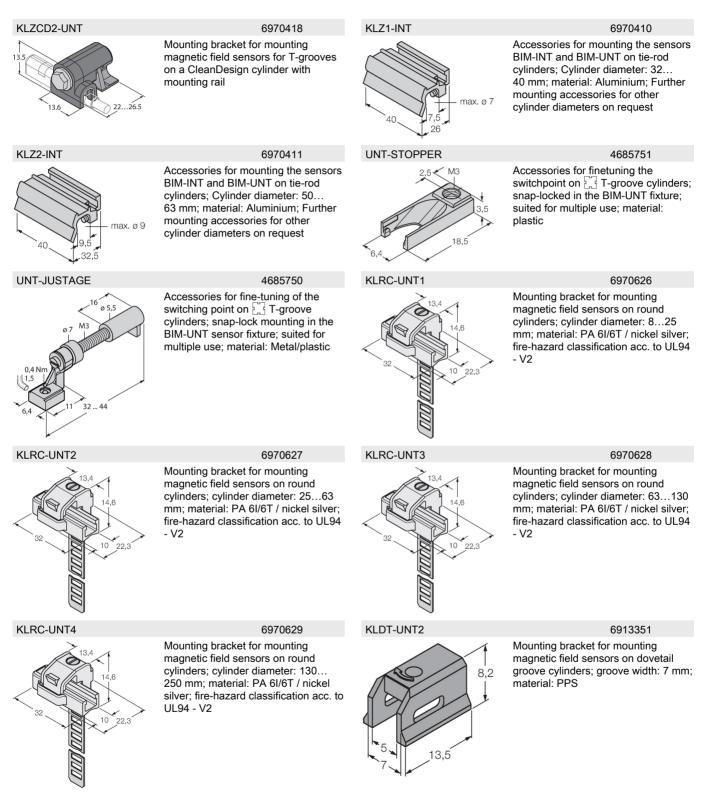


Thanks to the mounting lip, the sensor can be inserted into the groove from above with one hand. Mount the sensors as follows using the patented wing screw: The wing screw and the female thread feature a left-hand thread. Two small plastic lips keep the screw in position, small plastic lips keep the screw in position, ready-to-install. Turn the screw clockwise. The screw moves out of the thread and hits the upper grooves with the wings. The sensor is thus pressed down and locked in position. A few degrees up to approximately 1.5 turns of the screw with a slotted screwdriver (blade width 0.5 mm) or a 1.5 mm Allen key are sufficient to ensure vibration-proof fastening, depending on the shape of the slot. A tightening torque of 0.4 Nm is sufficient for safe mounting without damaging the cylinder. The sensor can now withstand an axial and radial tensile load of F=100N applied on the cable. A cable clip is included in the scope of delivery. It enables smooth cable routing in the groove and ensures that the cable is fastened as securely as possible. The corresponding accessories for mounting on other cylindrical housings must be ordered separately. ready-to-install. Turn the screw clockwise. The

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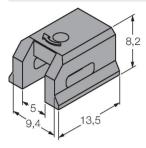
Accessories



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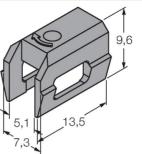
KLDT-UNT3



6913352

Mounting bracket for mounting magnetic field sensors on dovetail groove cylinders; groove width: 9.4 mm; material: PPS

KLDT-UNT6



6913355

Mounting bracket for mounting magnetic field sensors on dovetail groove cylinders; groove width: 7.35 mm; material: PPS